

How to make the most of a high resolution DEM (SPIRIT) over an Antarctic outlet glacier, test case of the Astrolabe Glacier, Terre Adélie sector, East Antarctica



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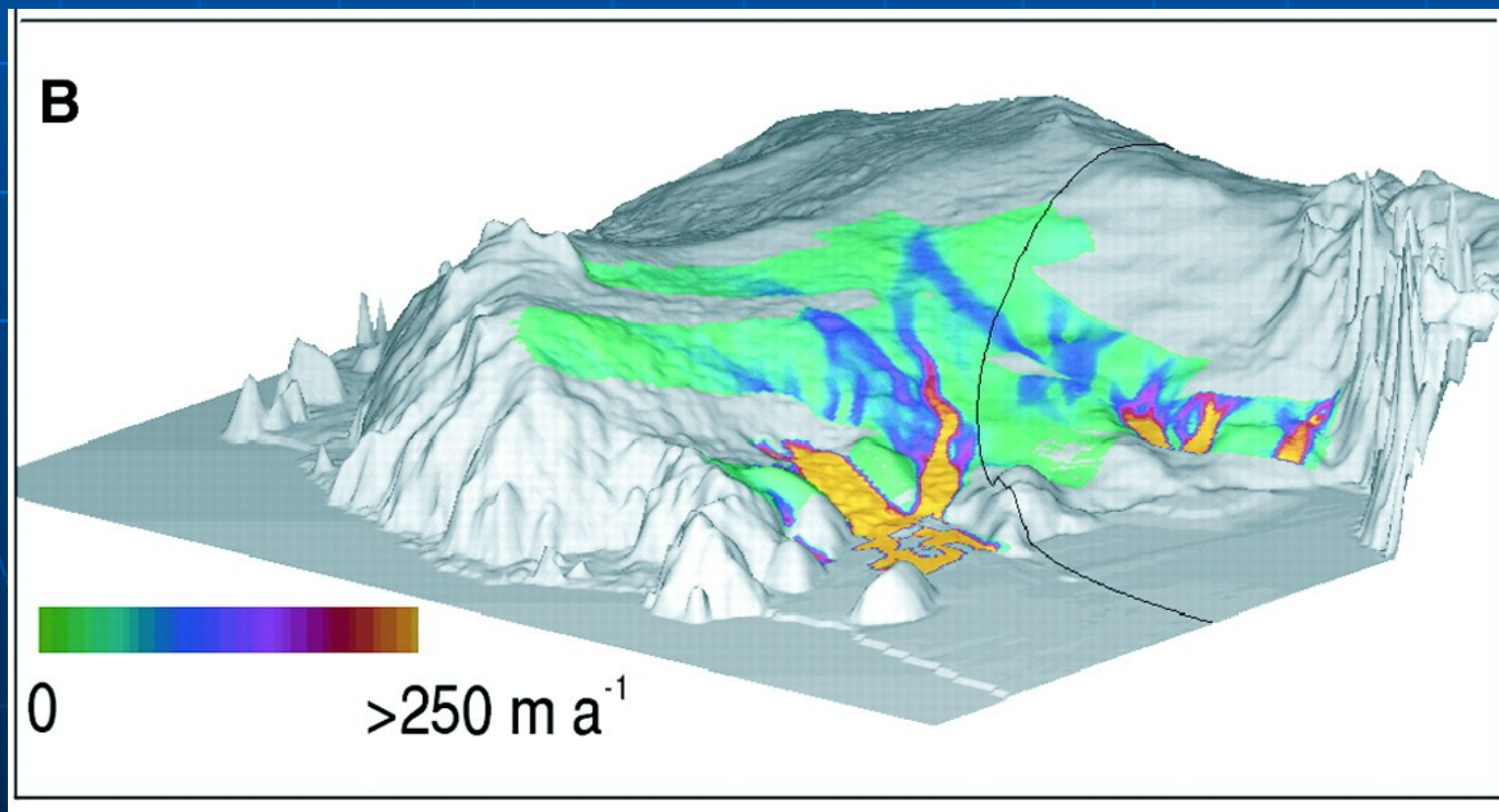
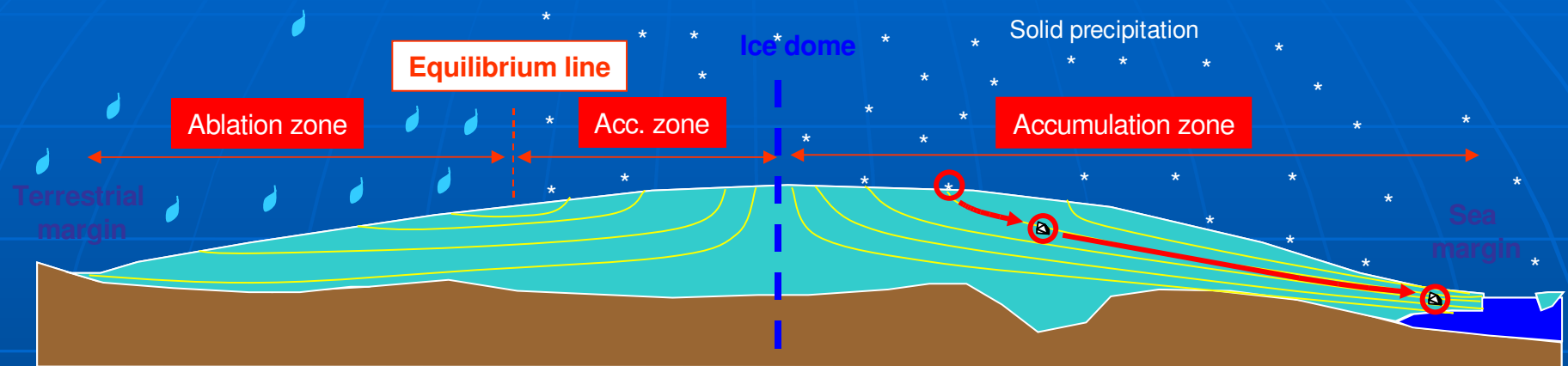
(4) L.G.G.E., S^T Martin d'Hères, France

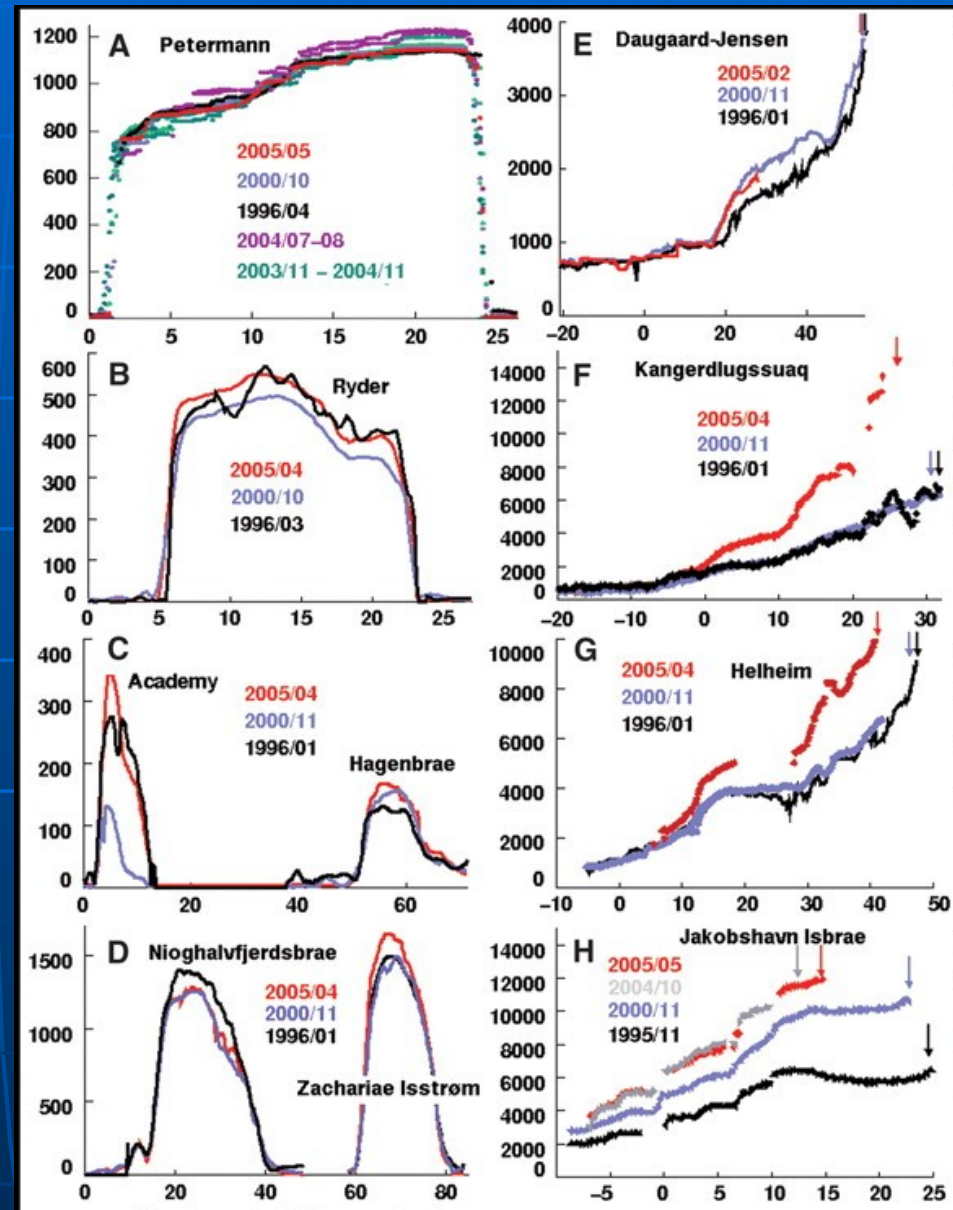
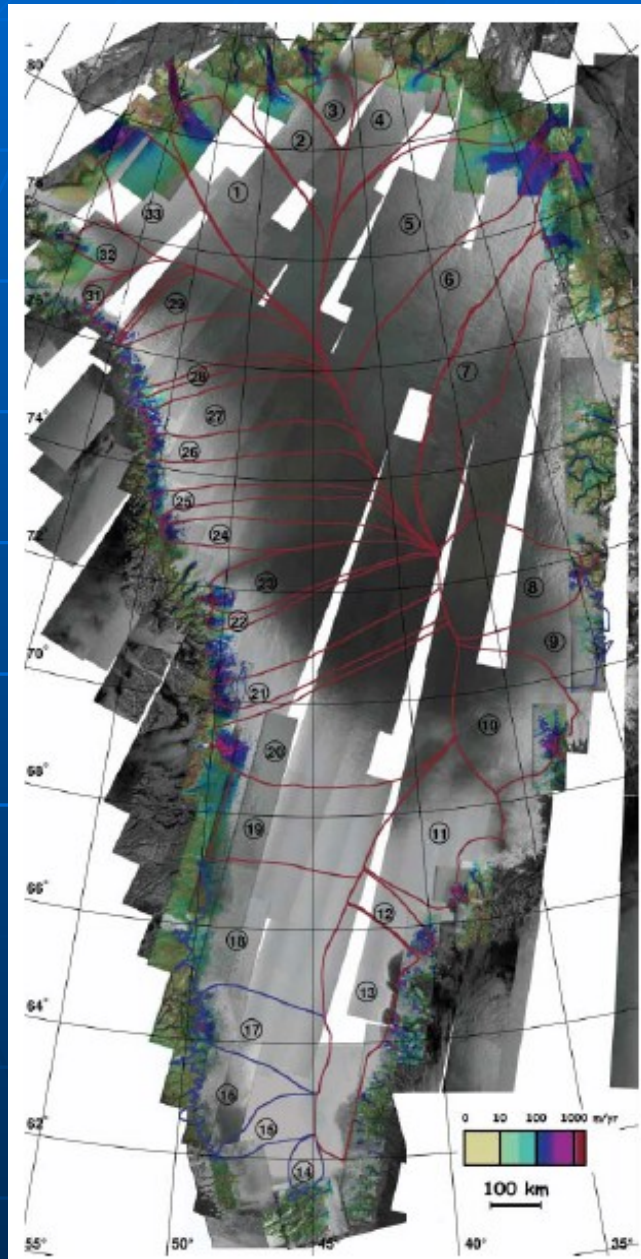
(5) LEGOS, Toulouse France



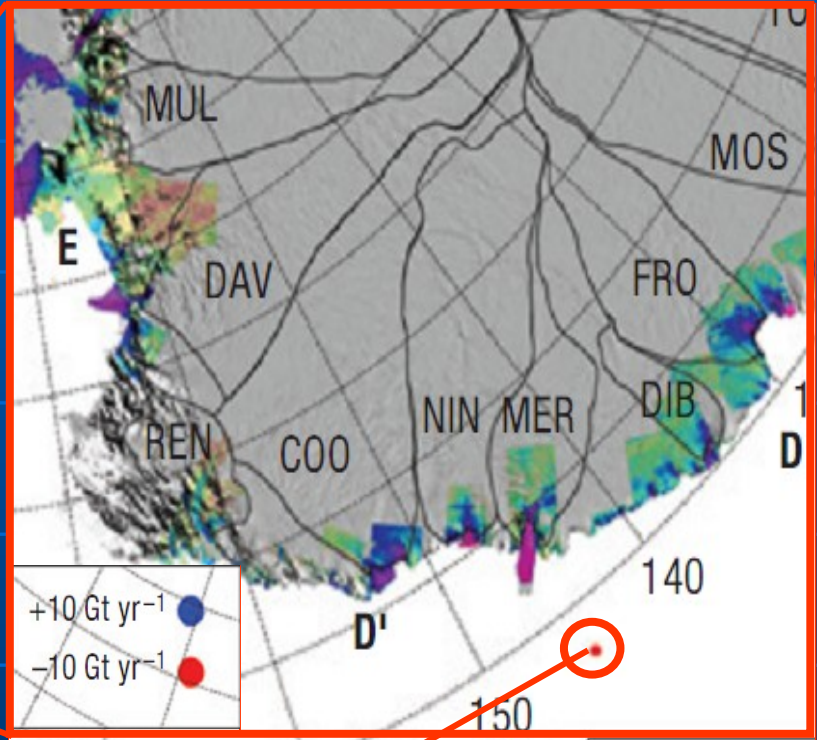
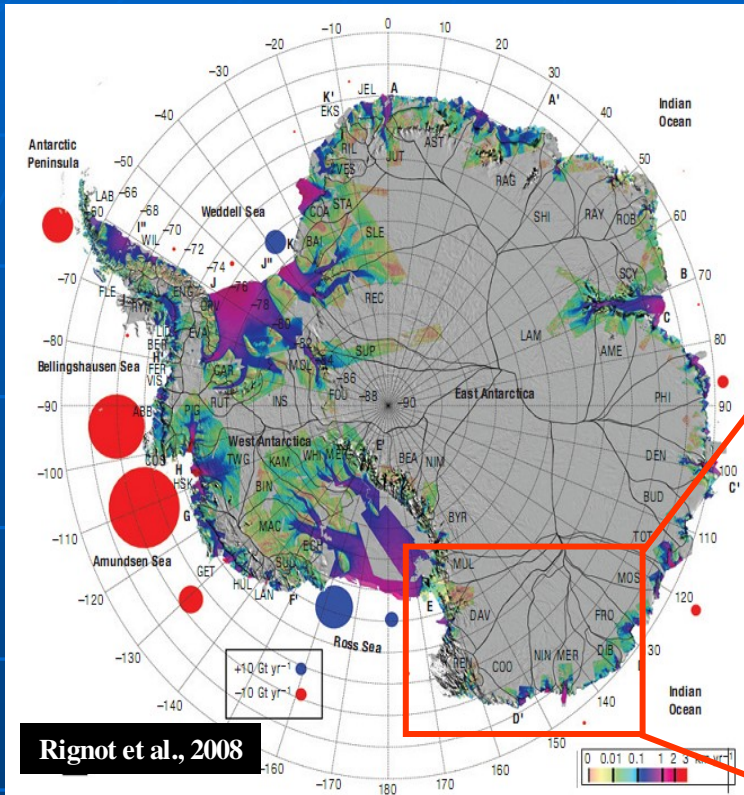
www-lgge.obs.ujf-grenoble.fr/axes/IPY/dacota







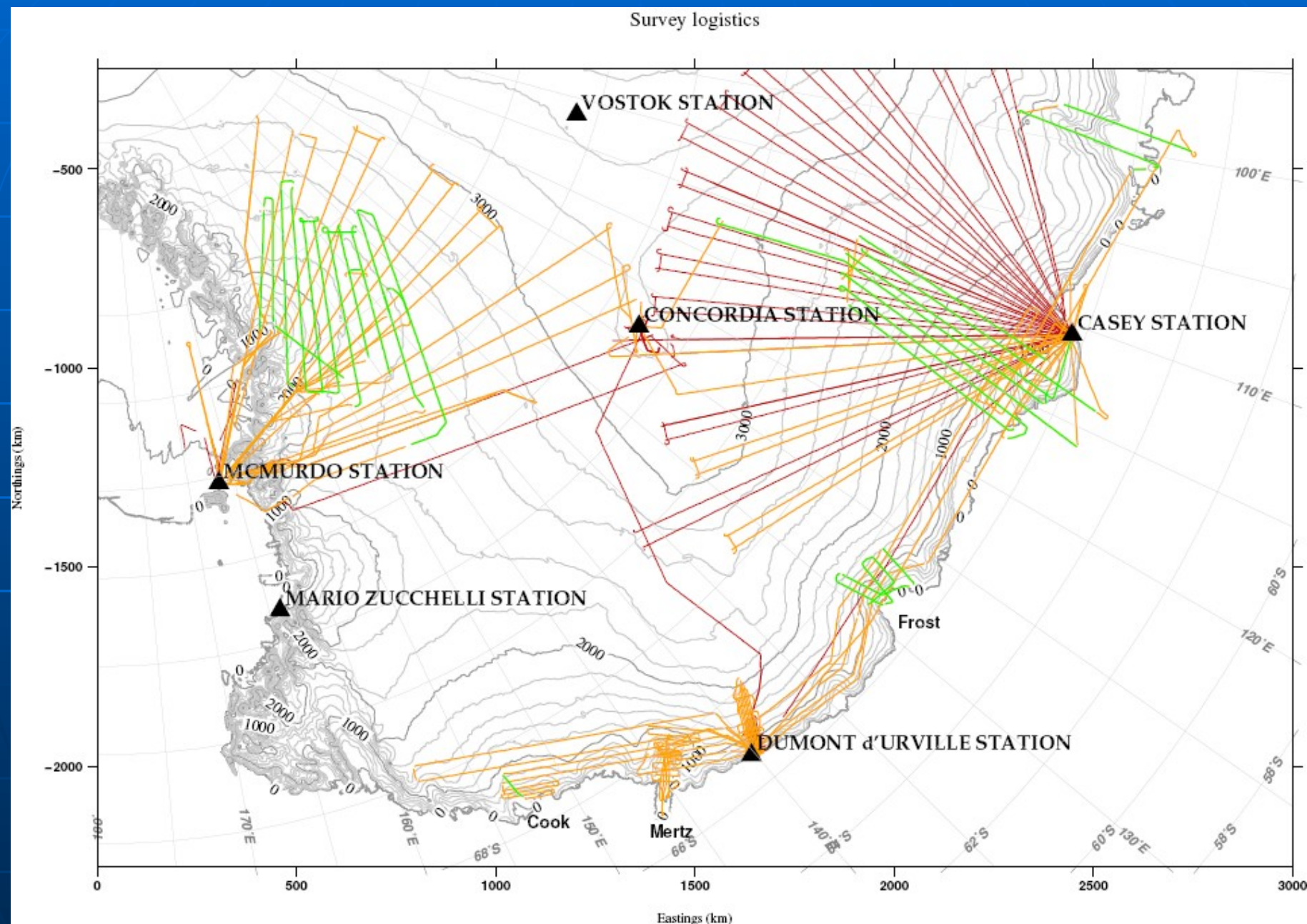
CONTEXT



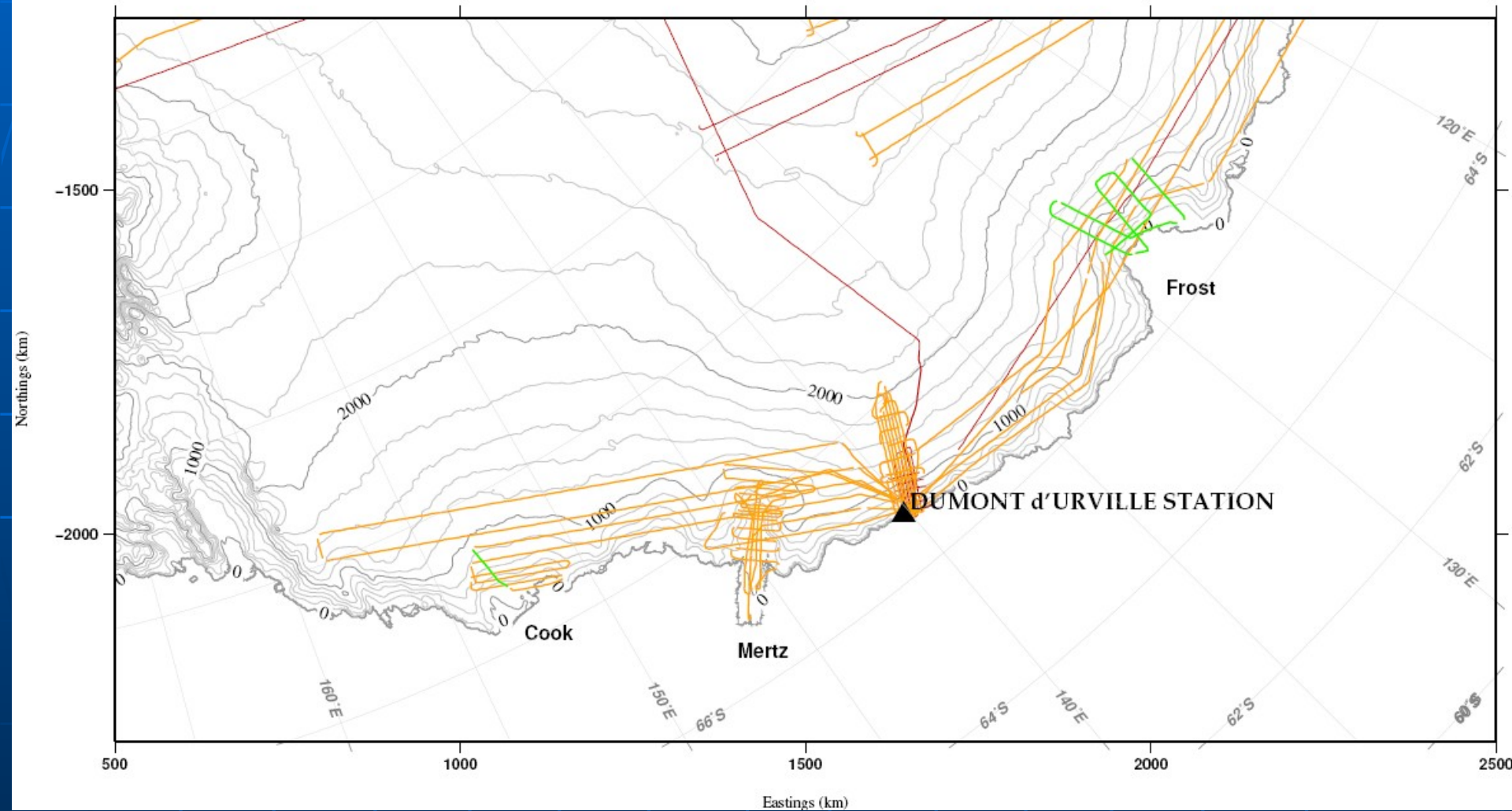
Large uncertainties in the overall mass balance of the East-Antarctic ice sheet (Wilkes sector)

$-2 \pm 19 \text{ Gt /yr}$

Need for a more accurate computation of the total ice flux to the sea through outlet glaciers

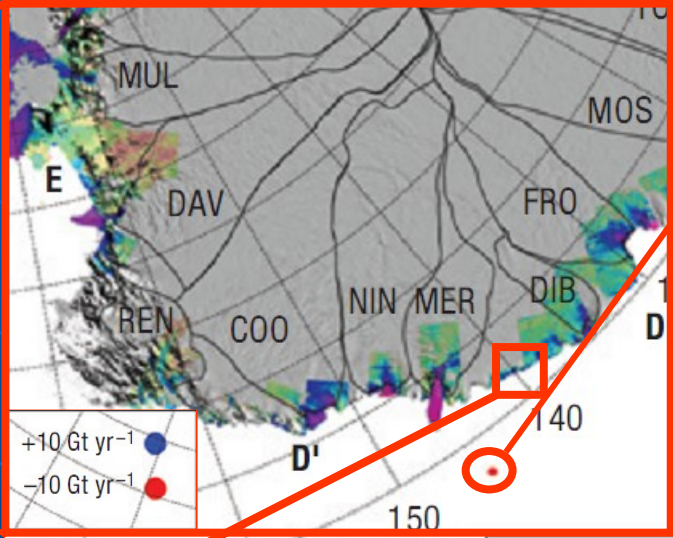
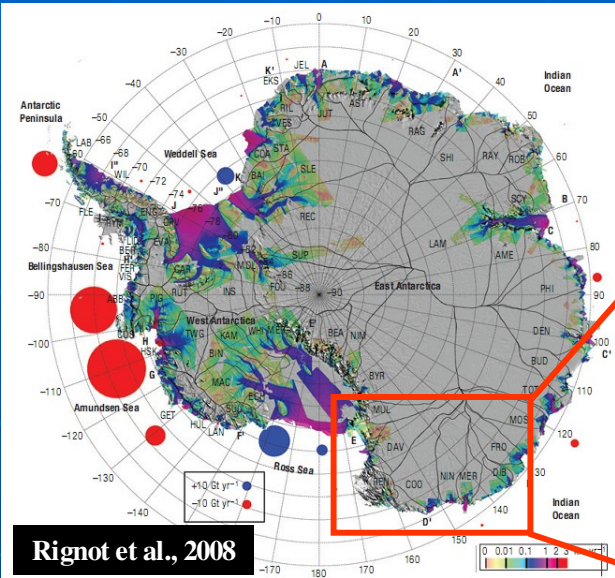


Survey logistics



CONTEXT

The Astrolabe glacier as a test zone



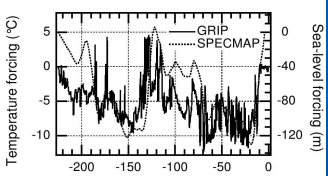
-2 ± 19 Gt /yr



Ice flow modelling and necessary field data

Environnemental forcing

Mass balance data



T

Sea level forcing

Core of the model

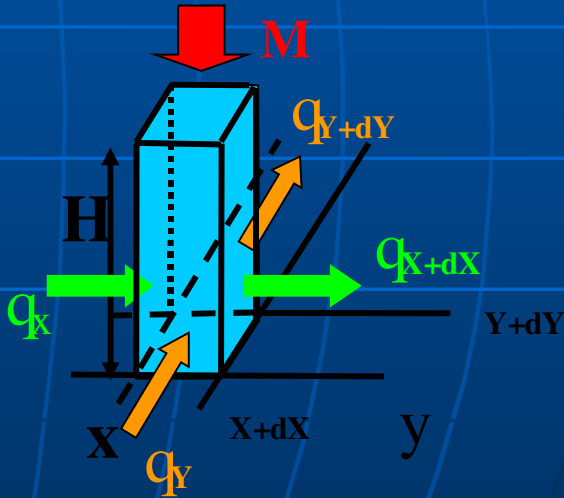
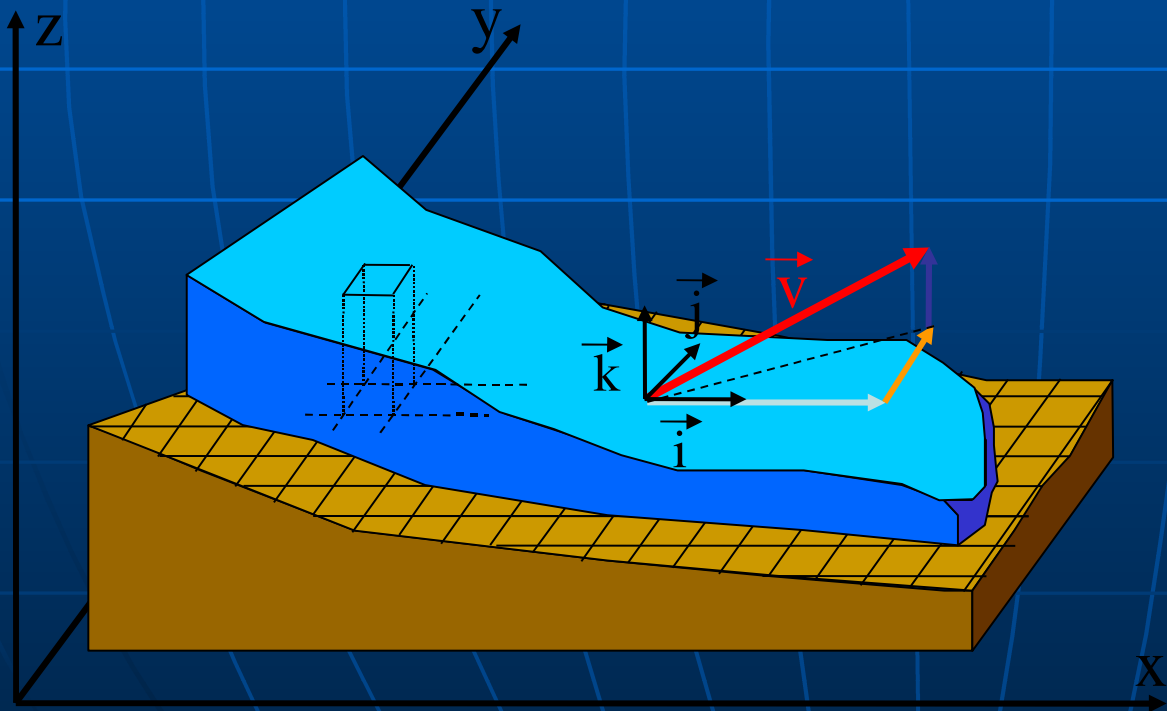
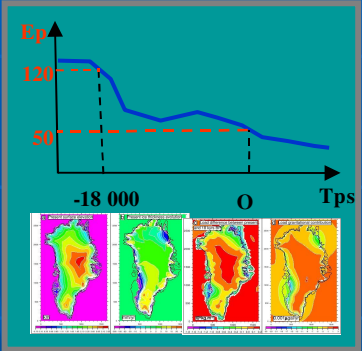
$$\begin{aligned} \nabla \cdot \boldsymbol{\tau}_i + \rho g_i &= 0, \quad i = x, y, z \\ \frac{\partial H}{\partial t} &= M - \nabla \cdot \mathbf{q} \quad ; \quad \mathbf{q} = \bar{\mathbf{v}}_H H = \int_h^{H+h} \mathbf{v}_H(z) dz \\ \frac{\partial T}{\partial t} &= \frac{1}{\rho c_p} \nabla \cdot (k \nabla T) - \mathbf{v} \cdot \nabla T + \frac{W}{\rho c_p} \end{aligned}$$

$$\epsilon'_{i,j} = A(T) \tau^{n-1} \tau'_{i,j}$$

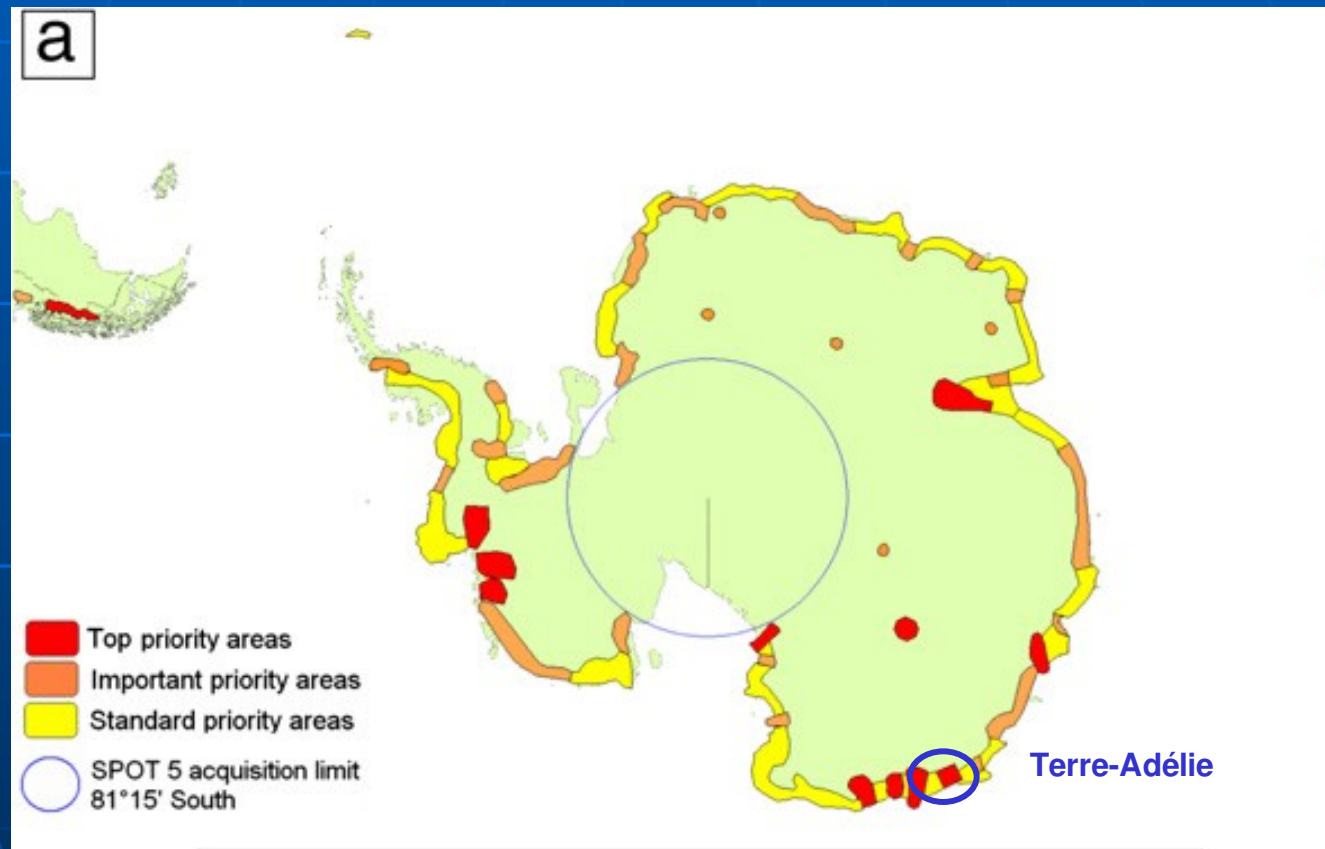
Sliding law

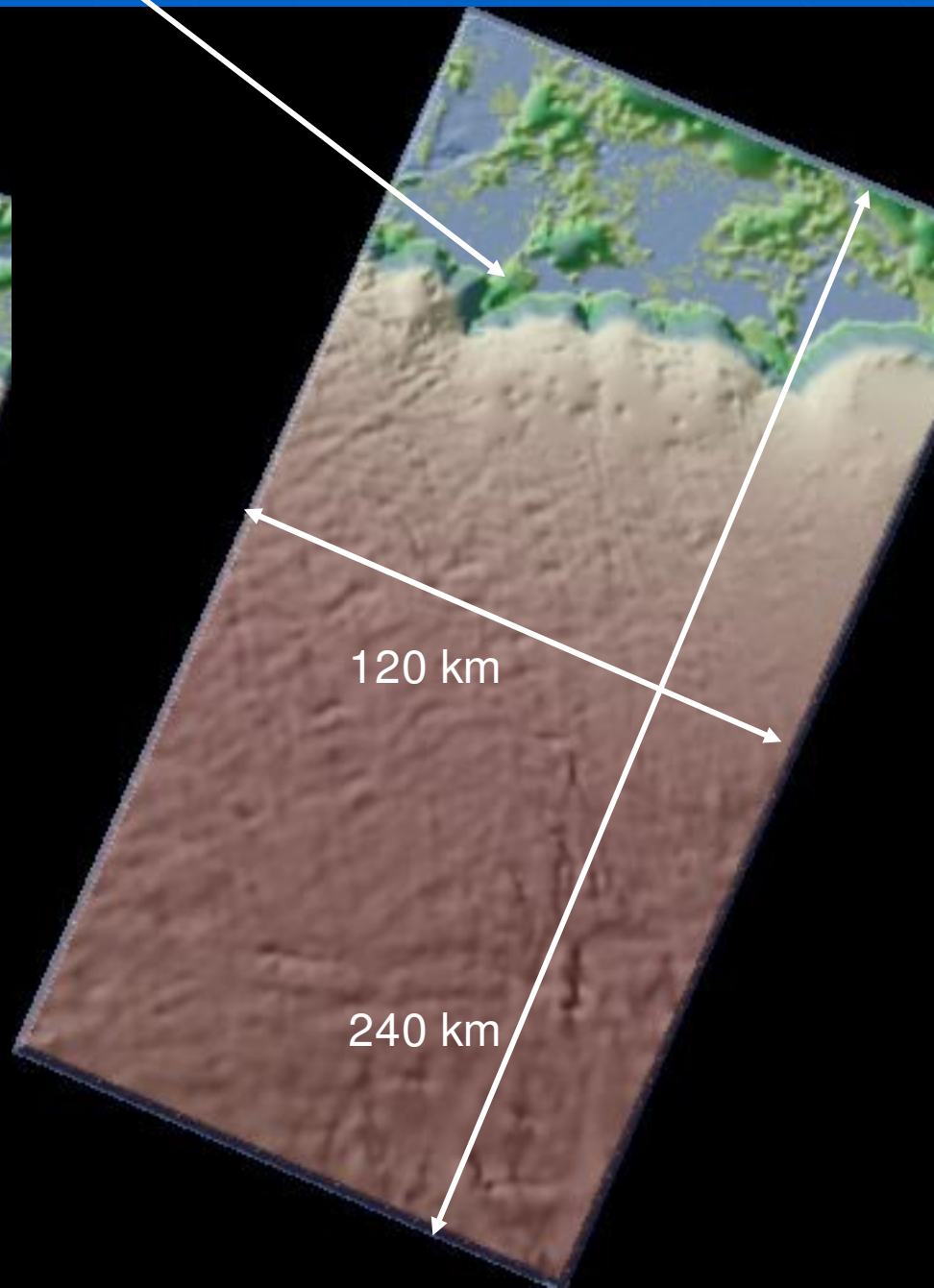
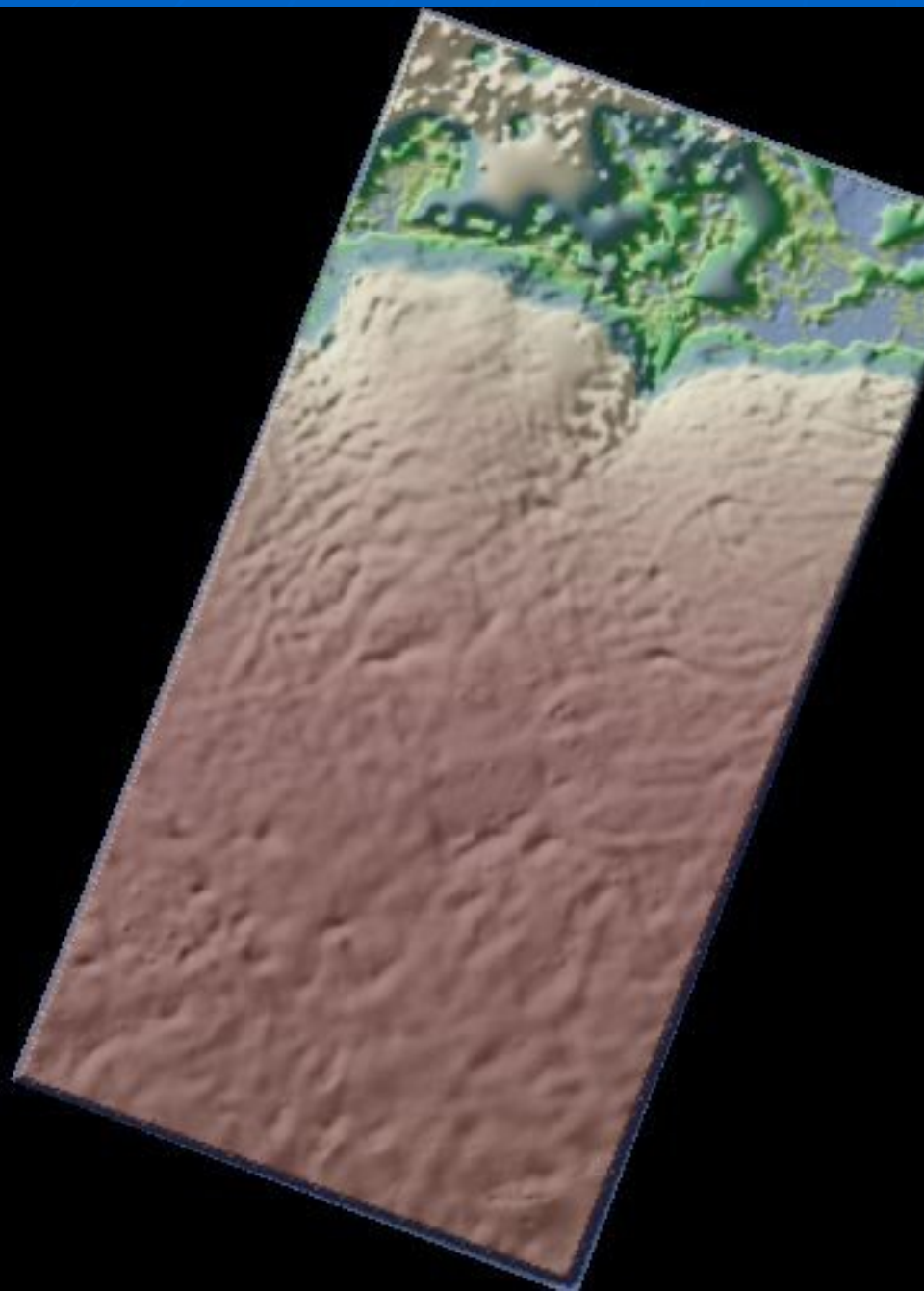
Grounding line dynamics

Model outputs

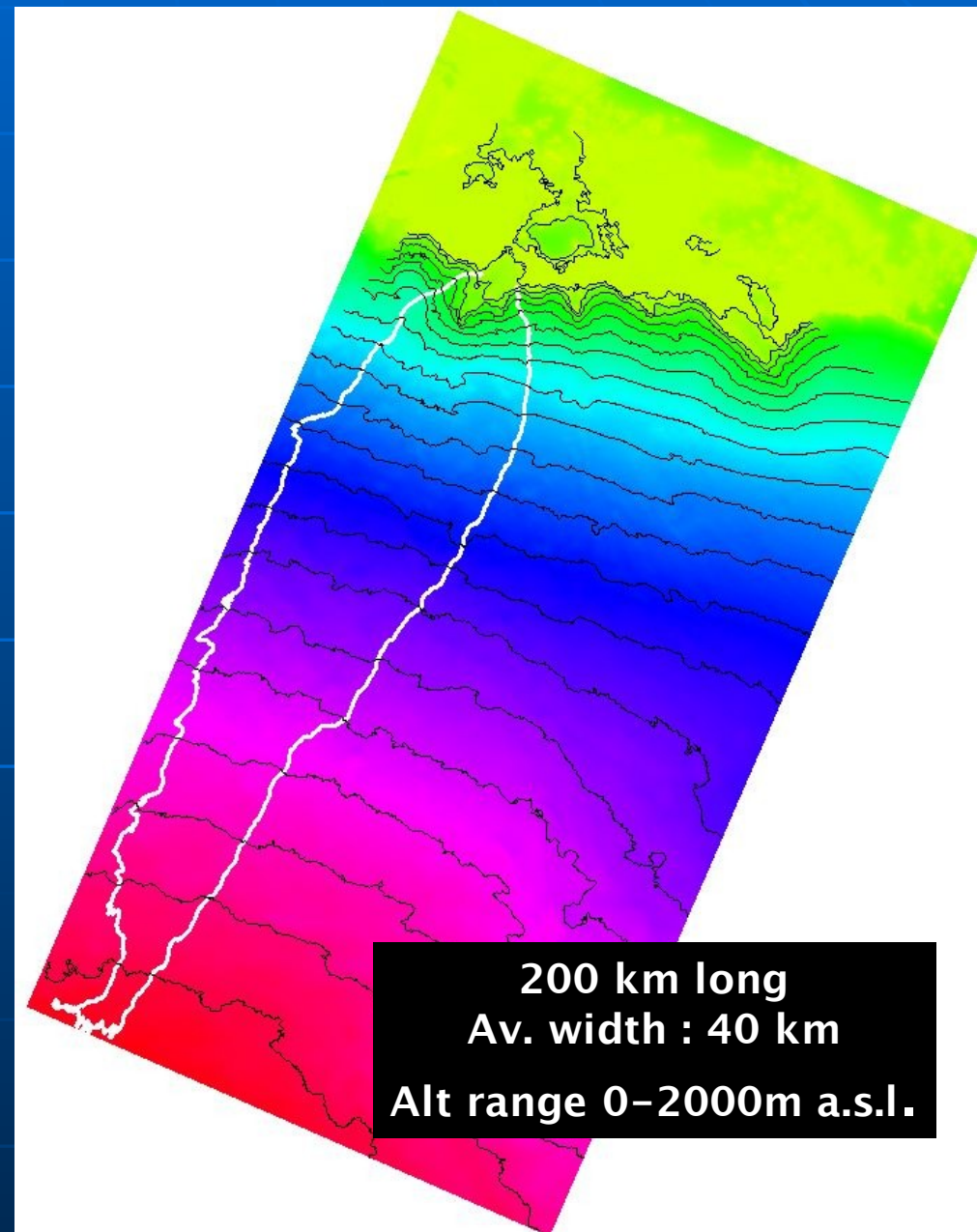
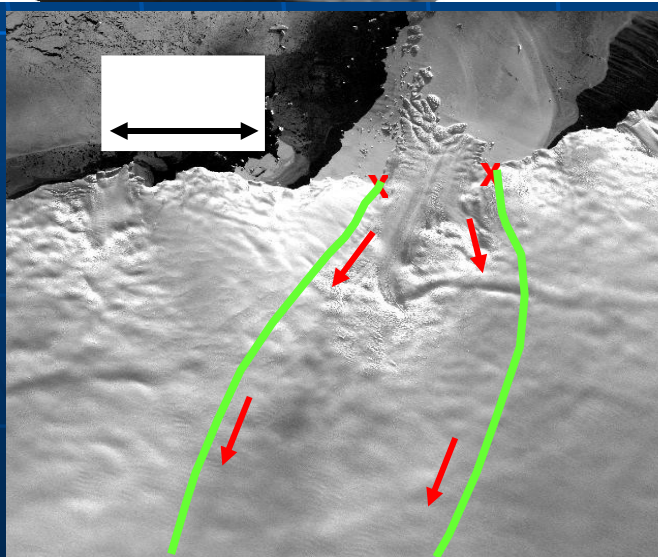
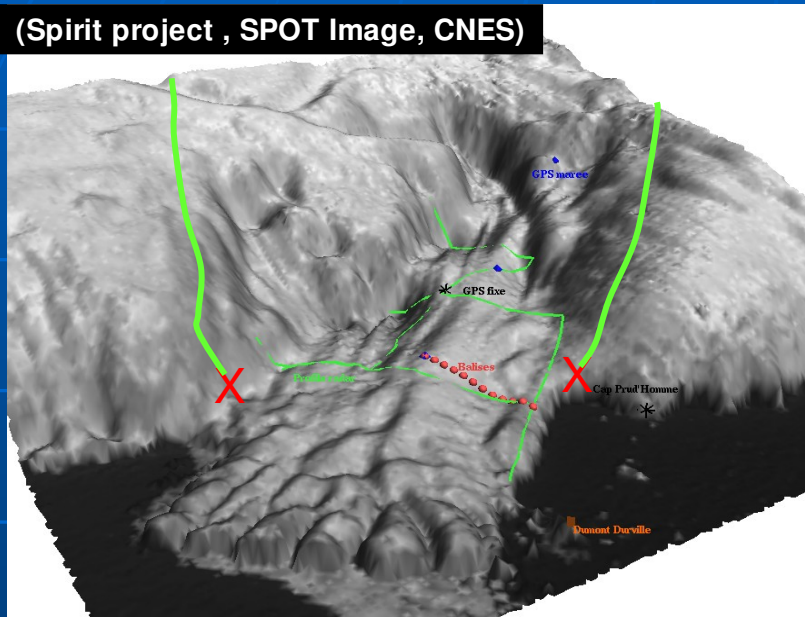


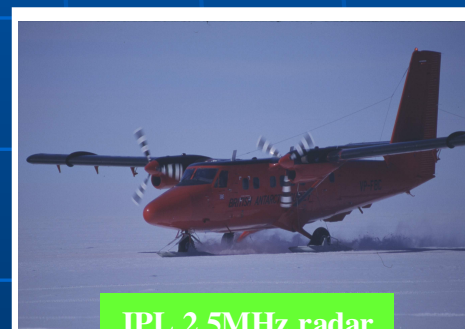
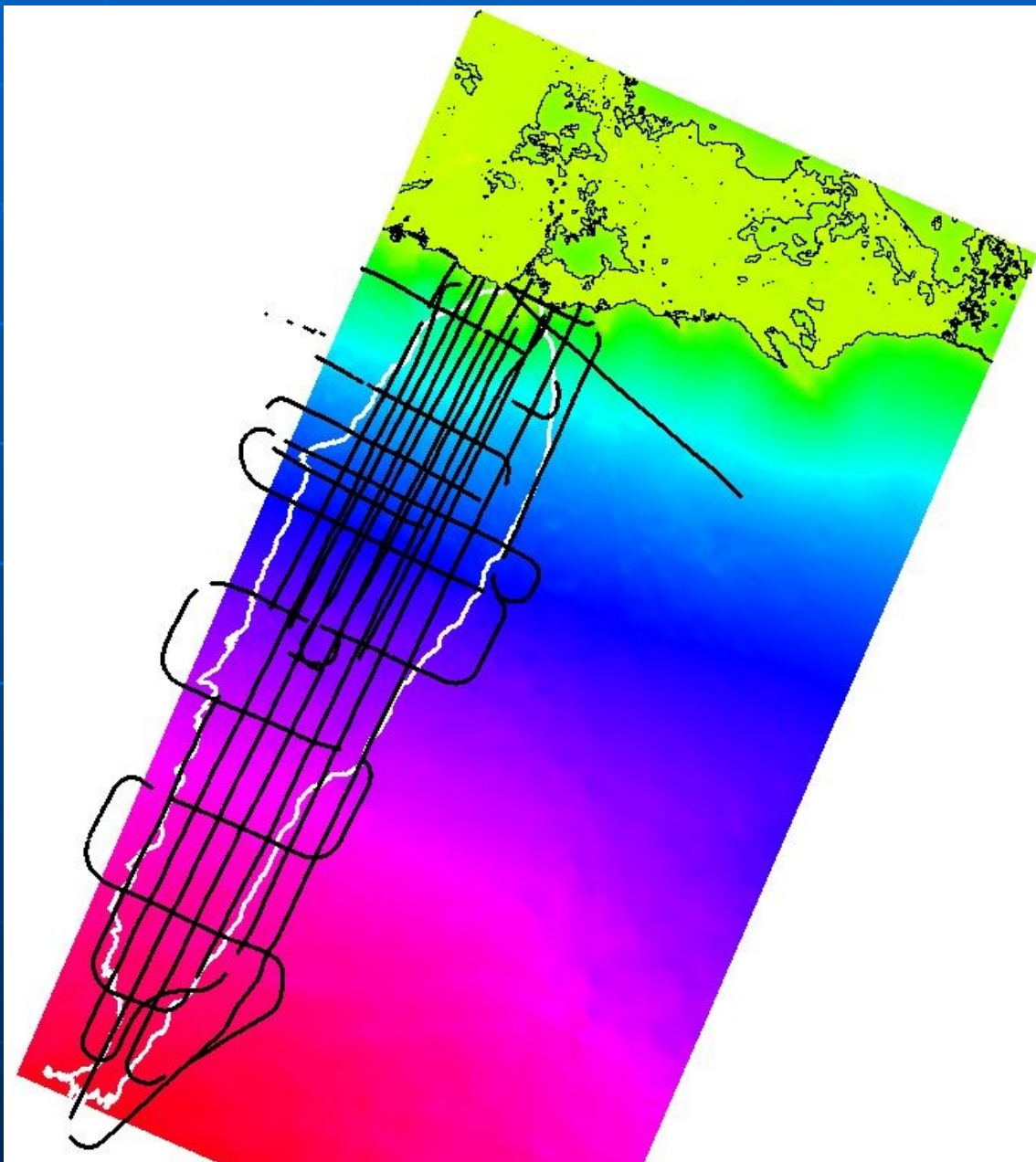
Areas of interest for the SPIRIT project in the Southern Hemisphere.





SPOT HRS stereographic pair -> DEM



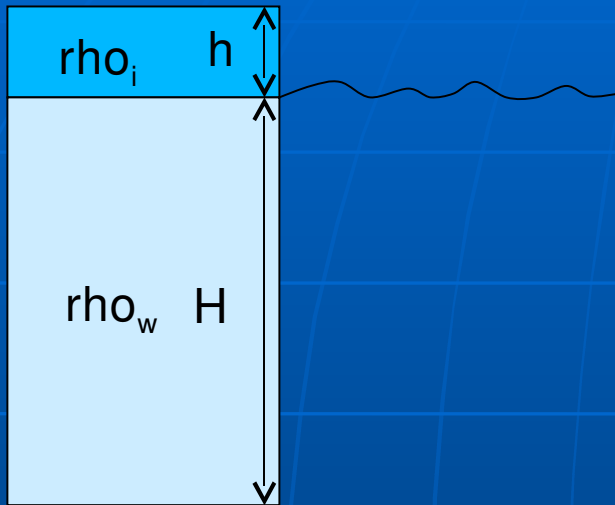


JPL 2.5MHz radar
(red grid)



Location of the Grounding line

On Topographic grounds.....



Flotation criterion :

$$H = h \cdot \rho_i / (\rho_w - \rho_i)$$

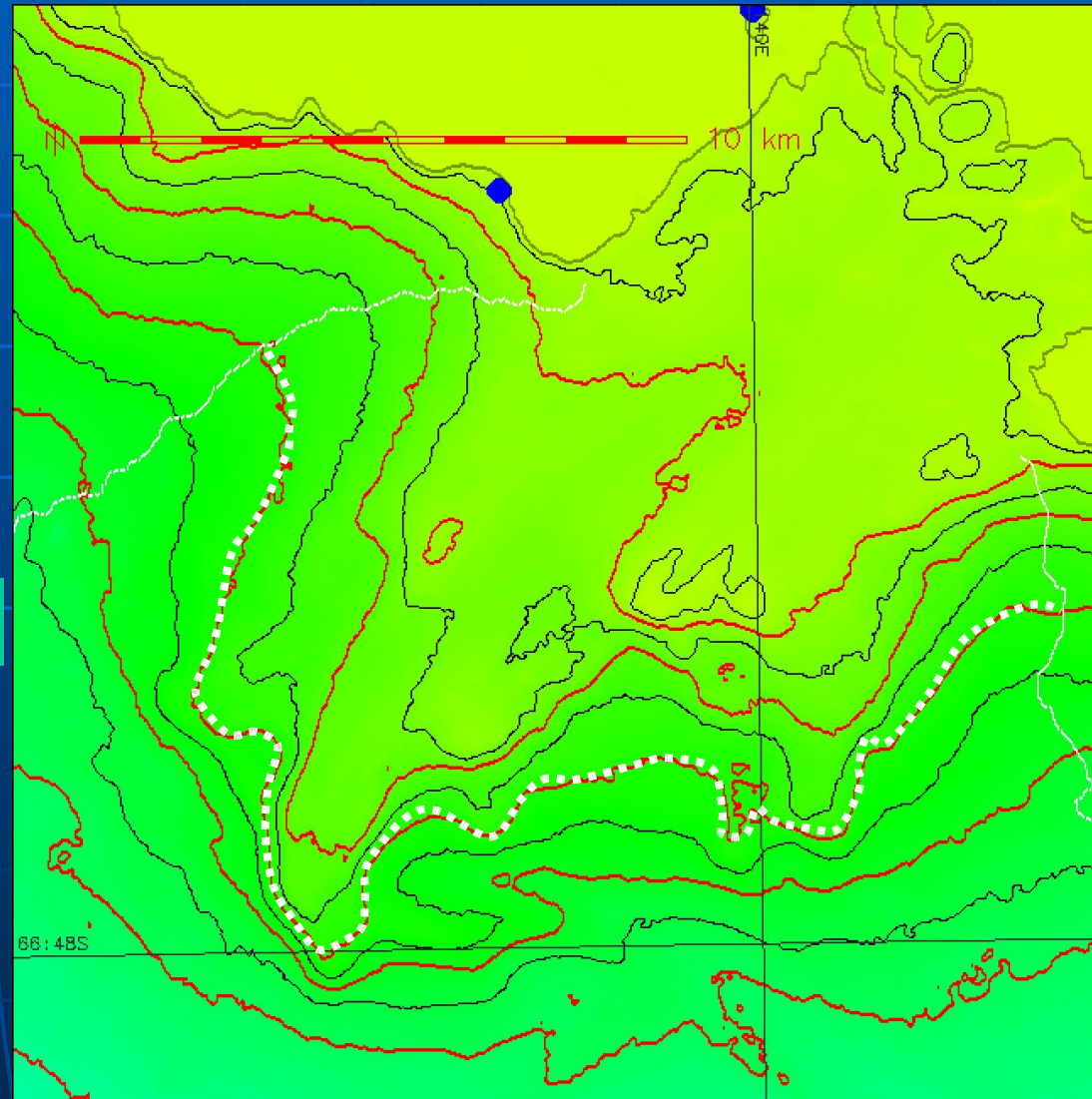
$$\rho_w = 1023 \text{ kg.m}^{-3}$$

$$\rho_i = 875 \text{ kg.m}^{-3}$$

$$H = 6 \cdot h$$

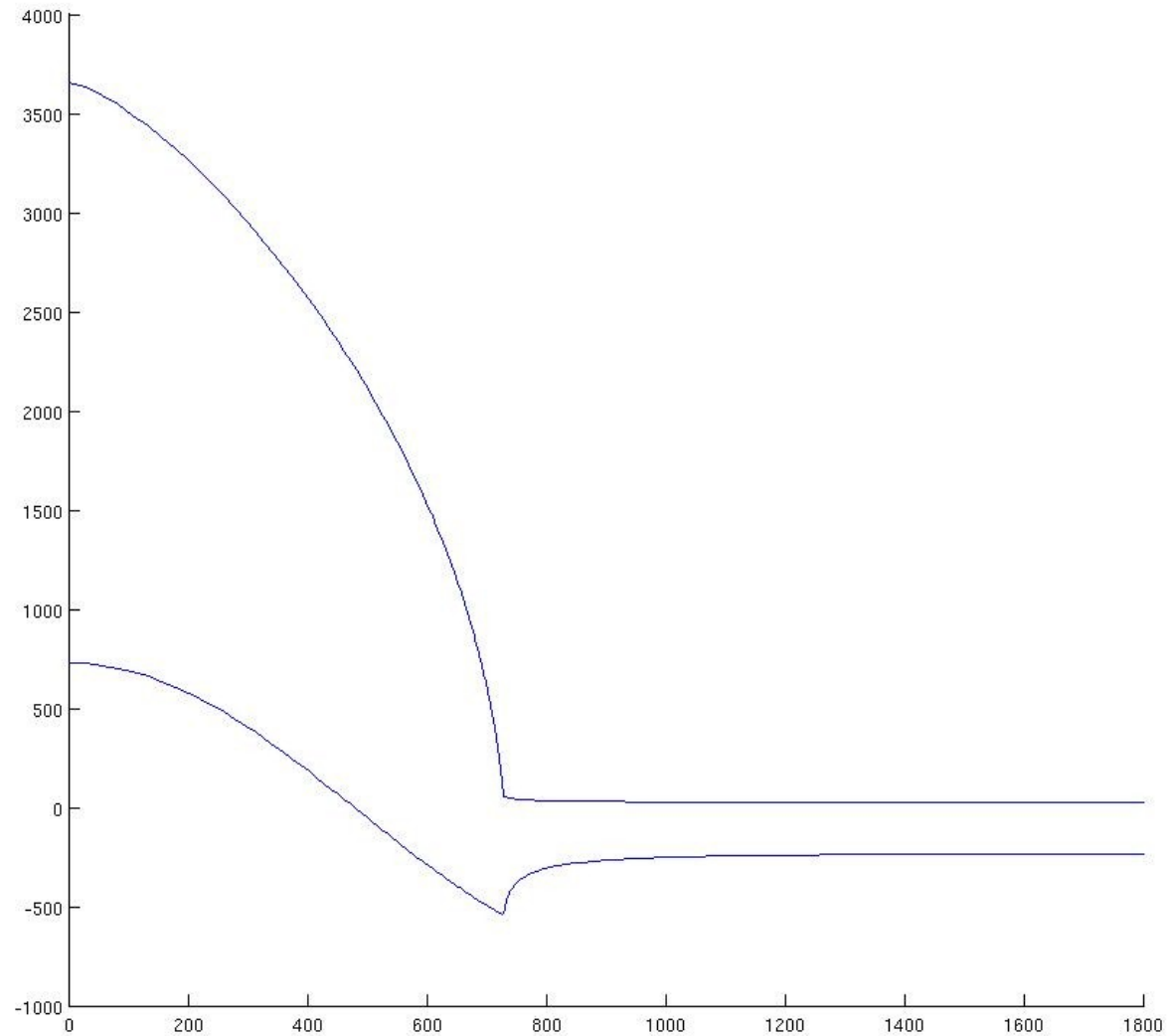
$$H_{\text{max}} : 1800\text{-}2000 \text{ m}$$

Maximum floating height
of about 300m



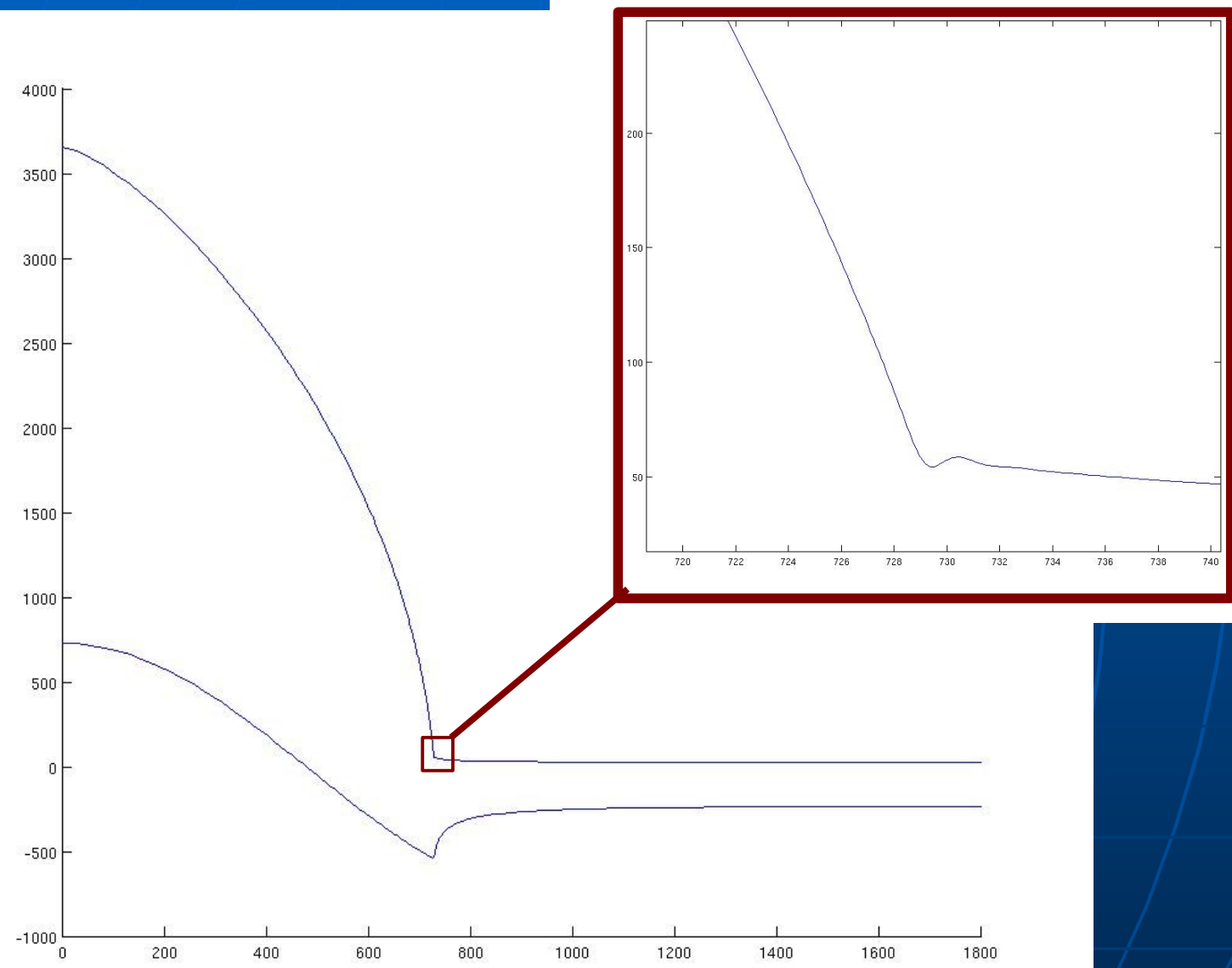
Marine ice-sheet – Model profile

Grounding line position from modelling



Marine ice-sheet – Model profile

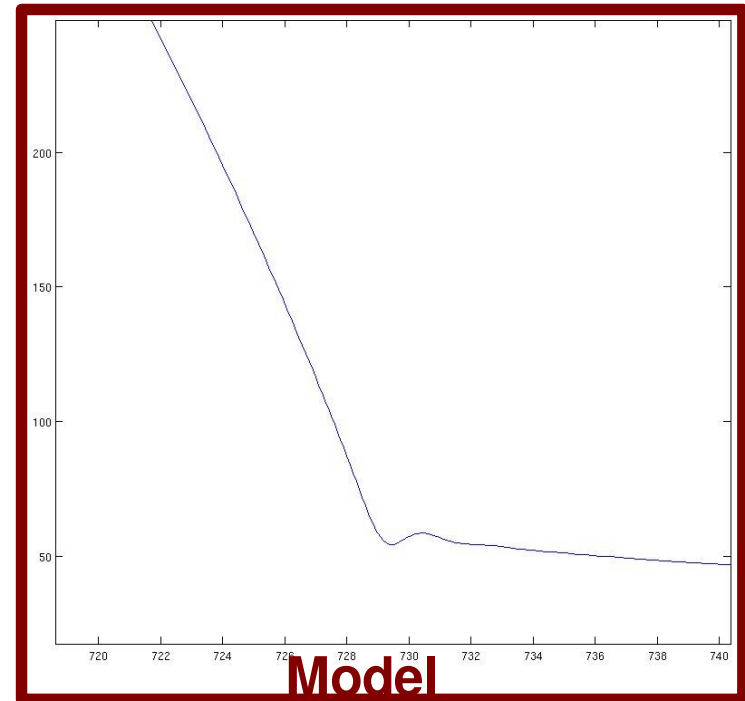
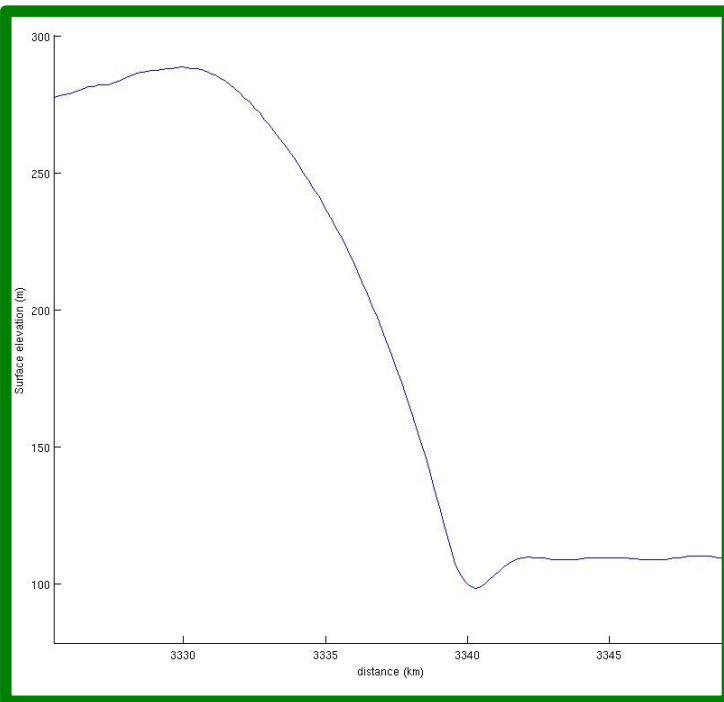
Grounding line position from modelling



Grounding line position from modelling

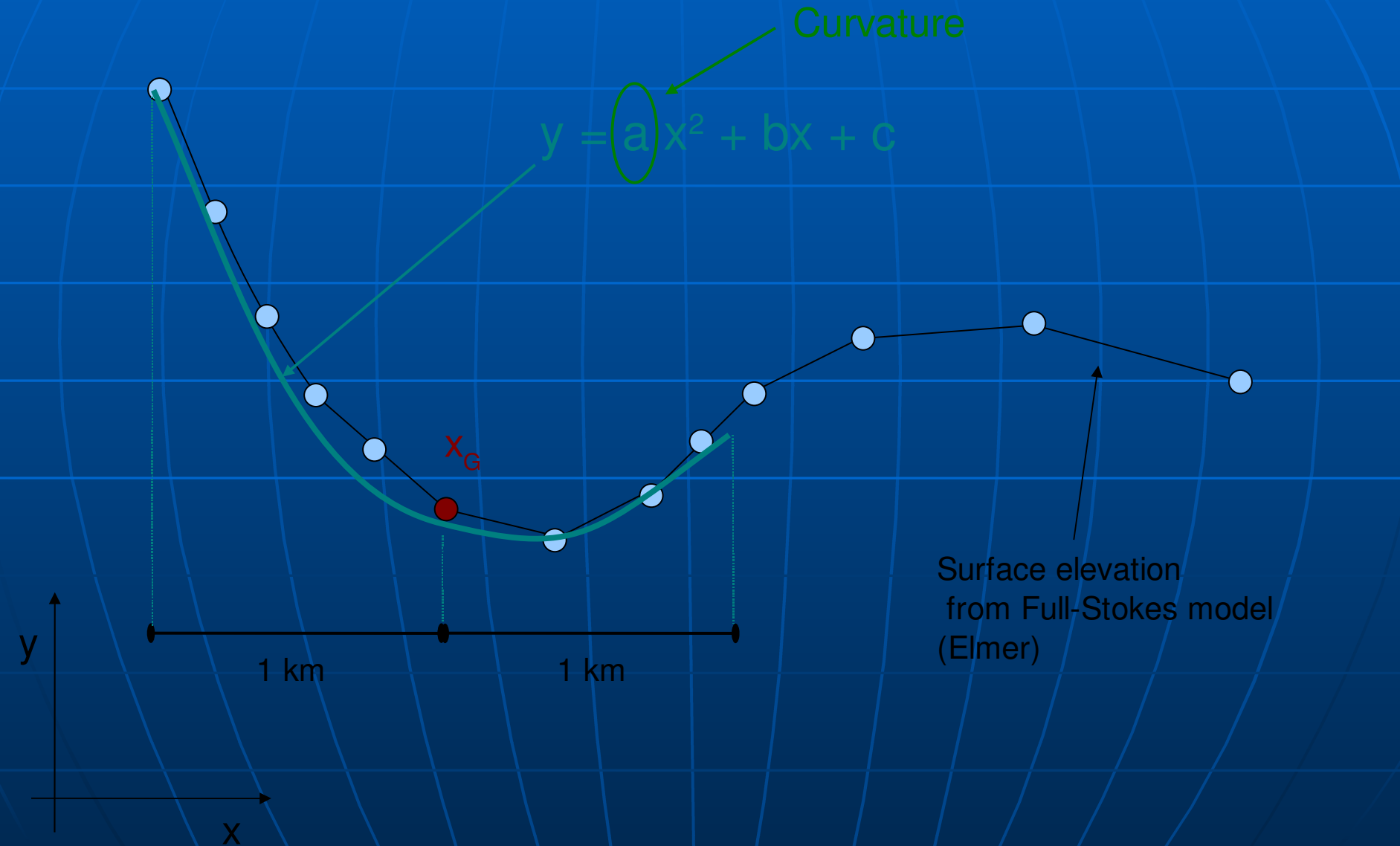
Surface elevation around
the grounding line :
model versus data

Data



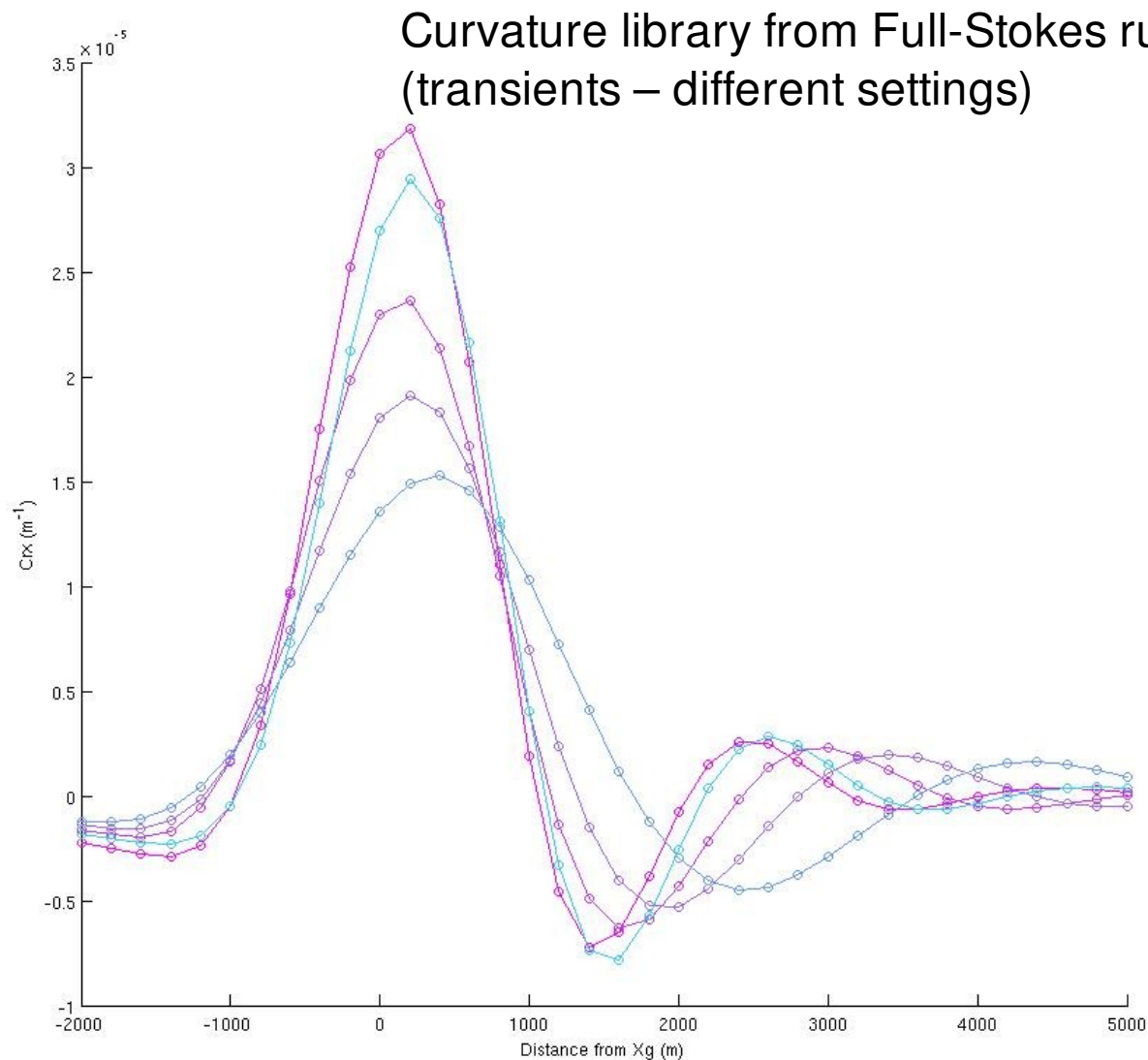
Quadratic curvature fitting
around the grounding line
(along a flow line)

Grounding line position from modelling

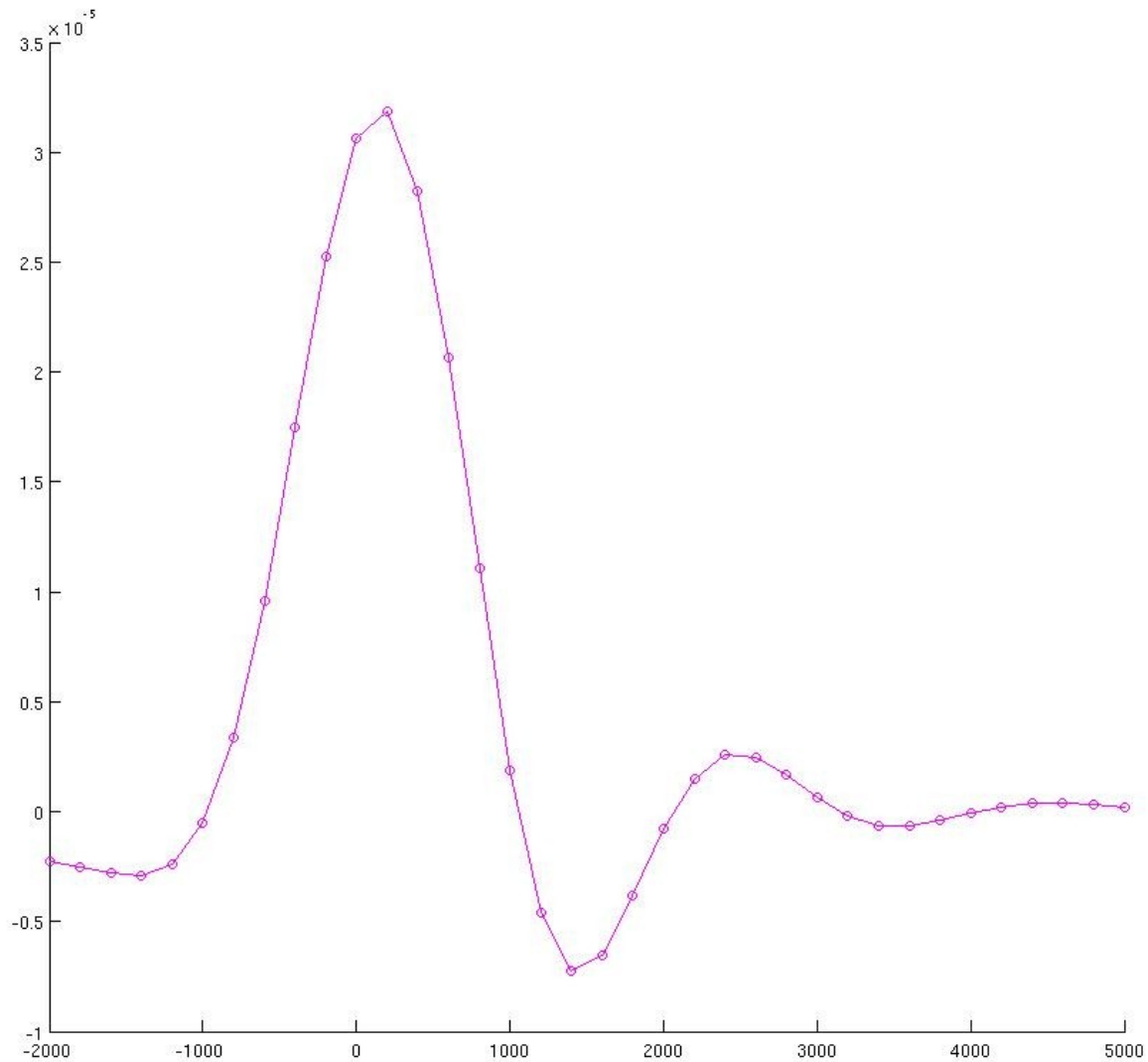


Runs under various conditions -> library of fitting curves

Grounding line position from modelling

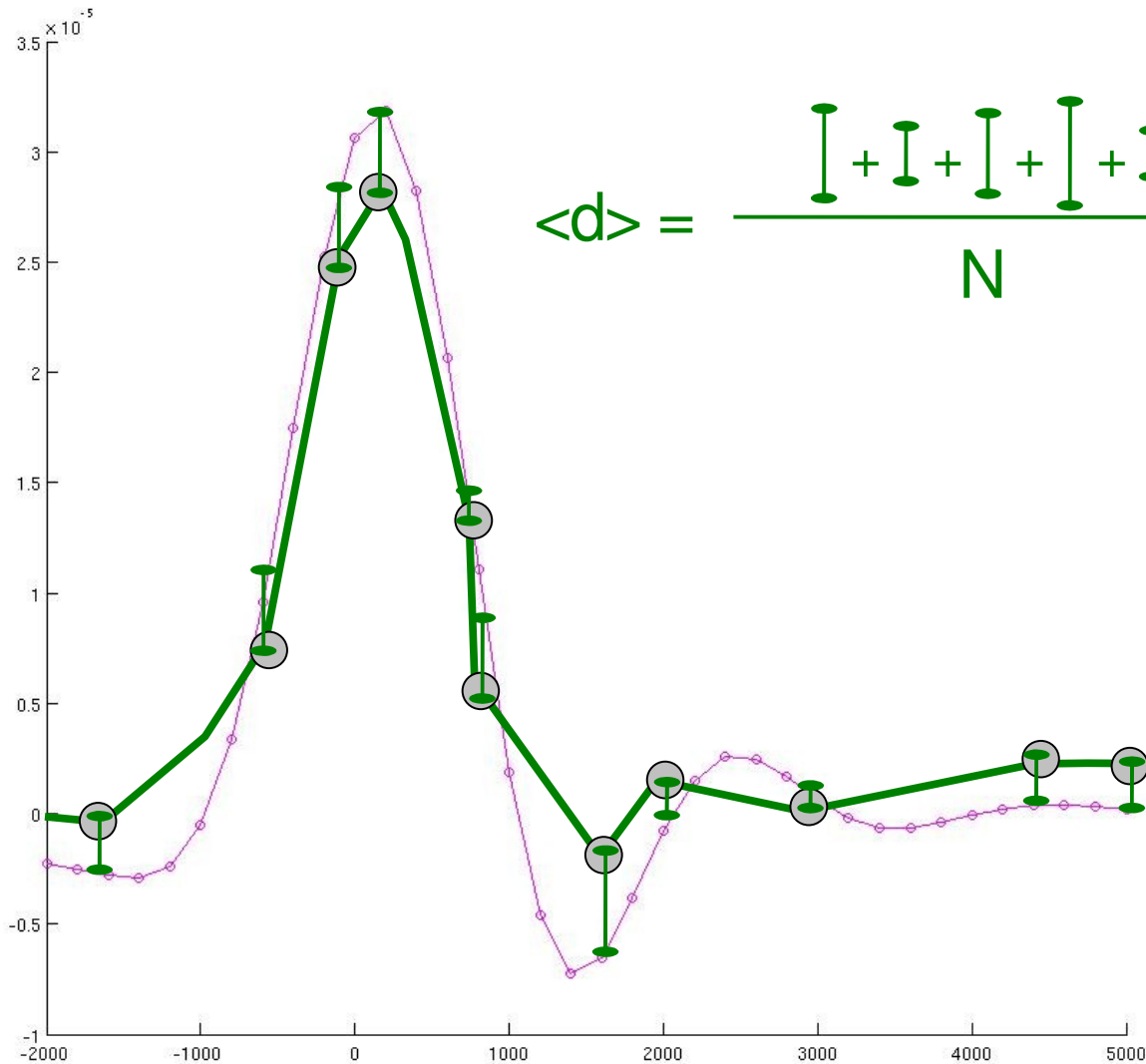


Grounding line position from modelling



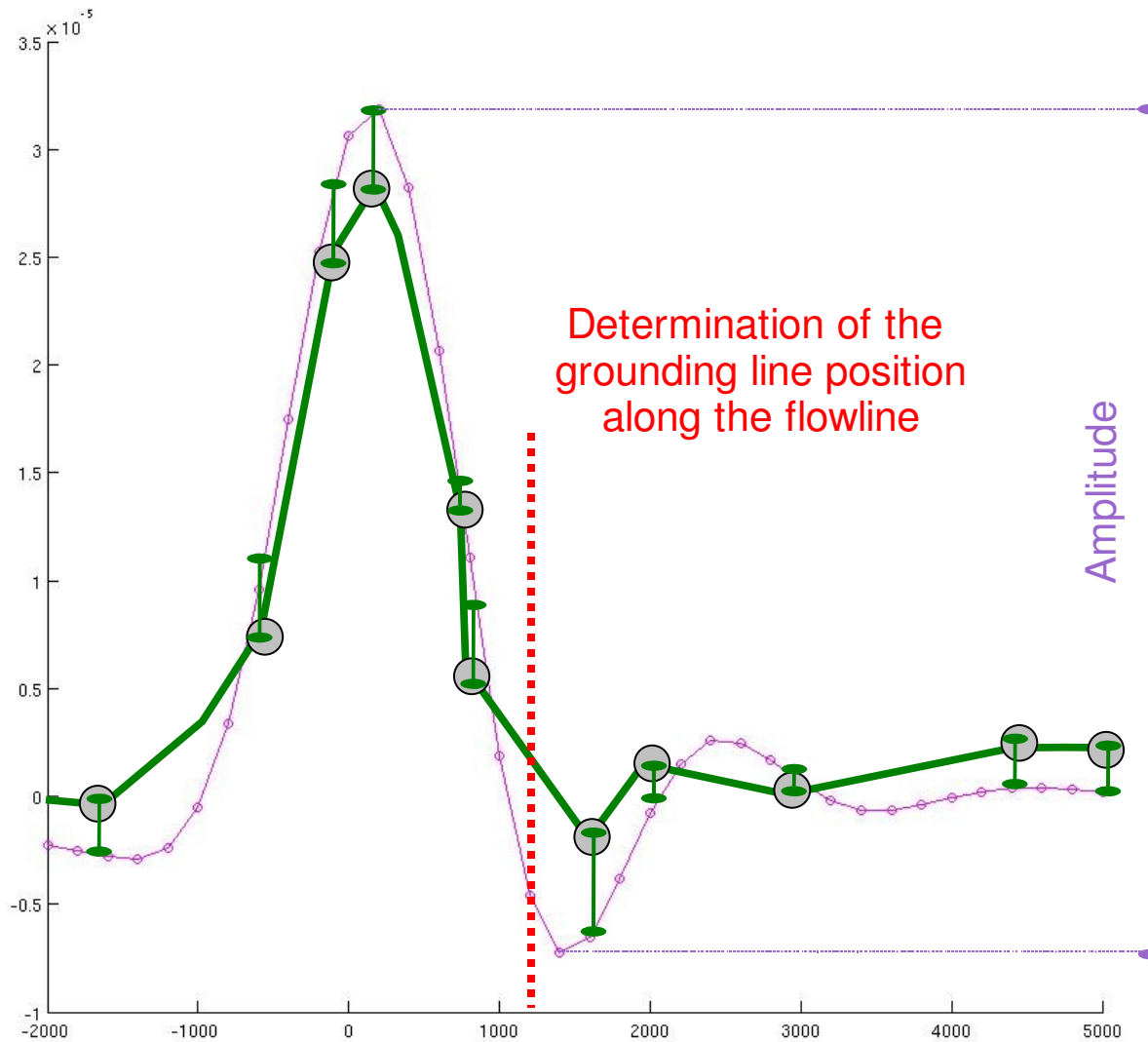
Minimizing the misfit → selection of the most appropriate curve

Grounding line position from modelling



$$\langle d \rangle = \frac{| \quad | + | \quad | + | \quad | + | \quad | + | \quad |}{N}$$

Grounding line position from modelling

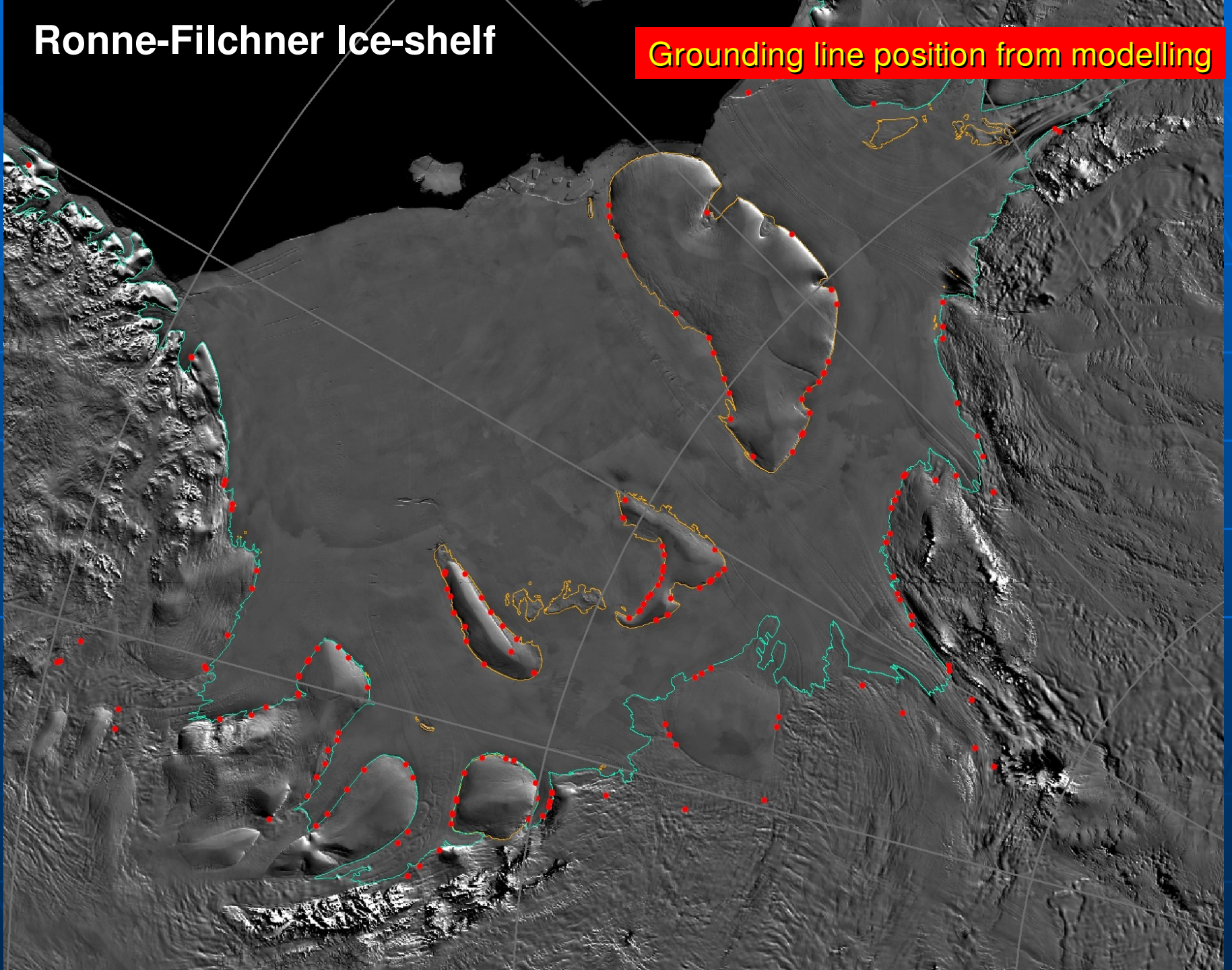


Determination of the
grounding line position
along the flowline

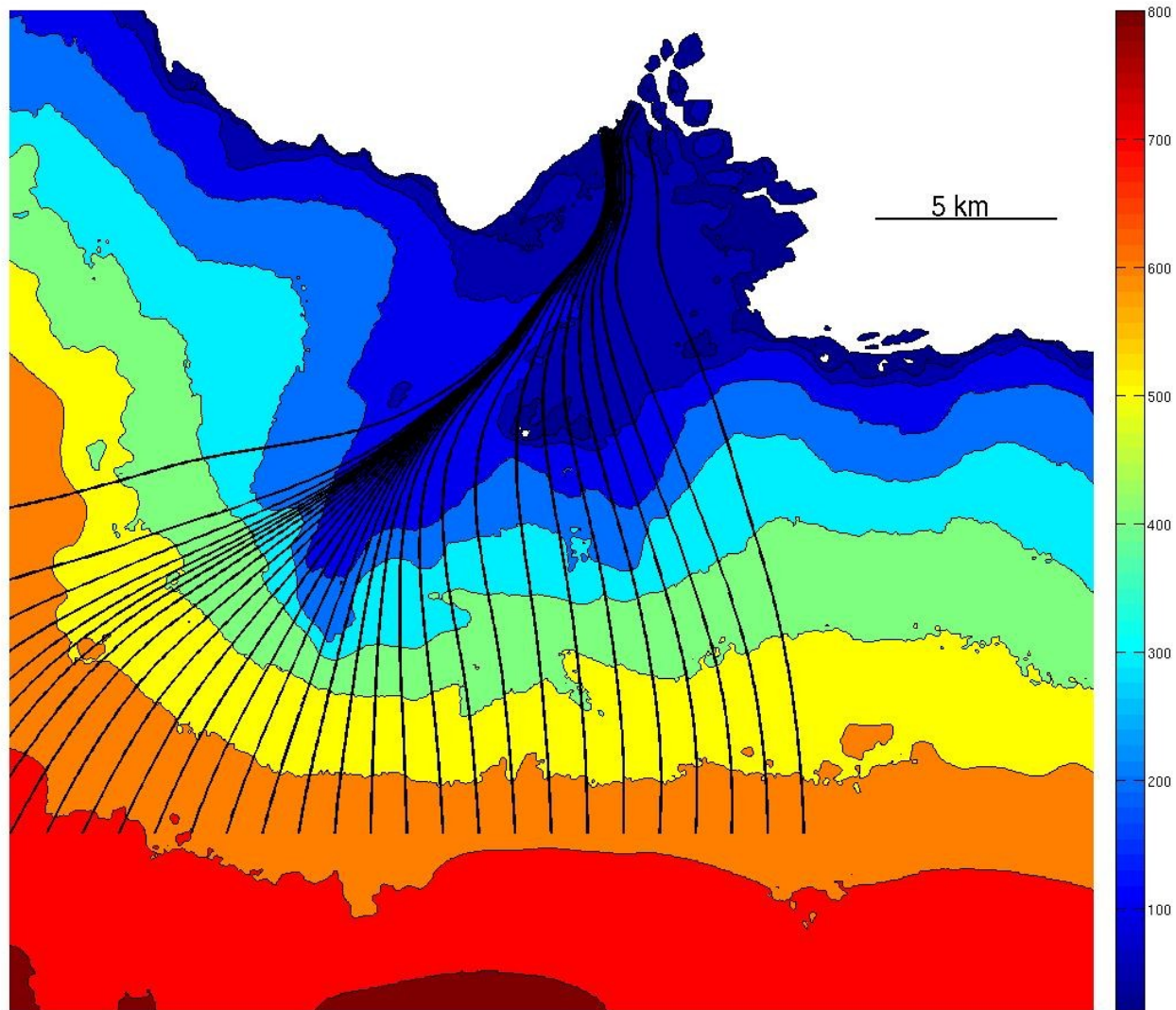
$$\frac{\langle d \rangle}{\text{Amplitude}} < 0.2$$

Ronne-Filchner Ice-shelf

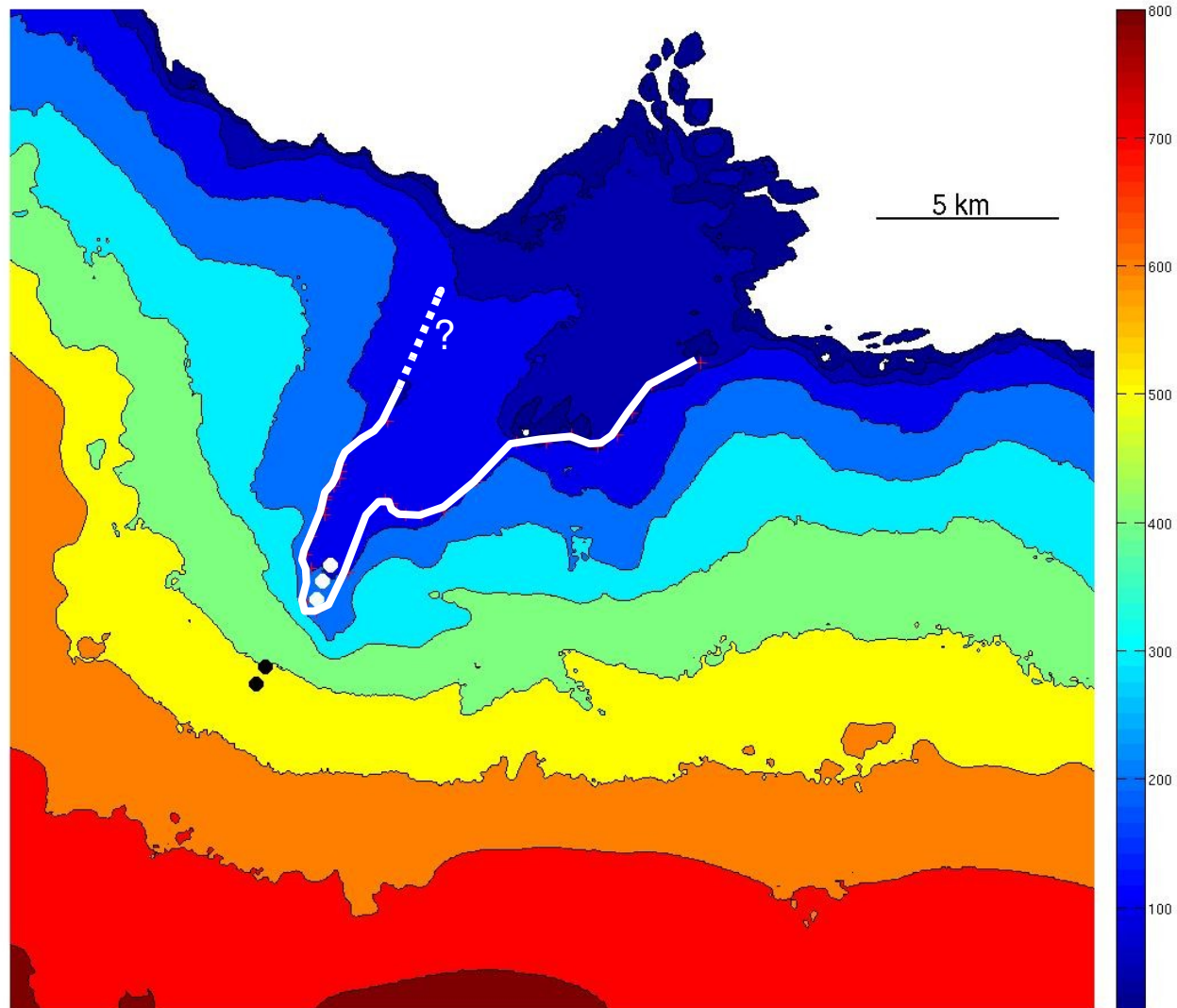
Grounding line position from modelling



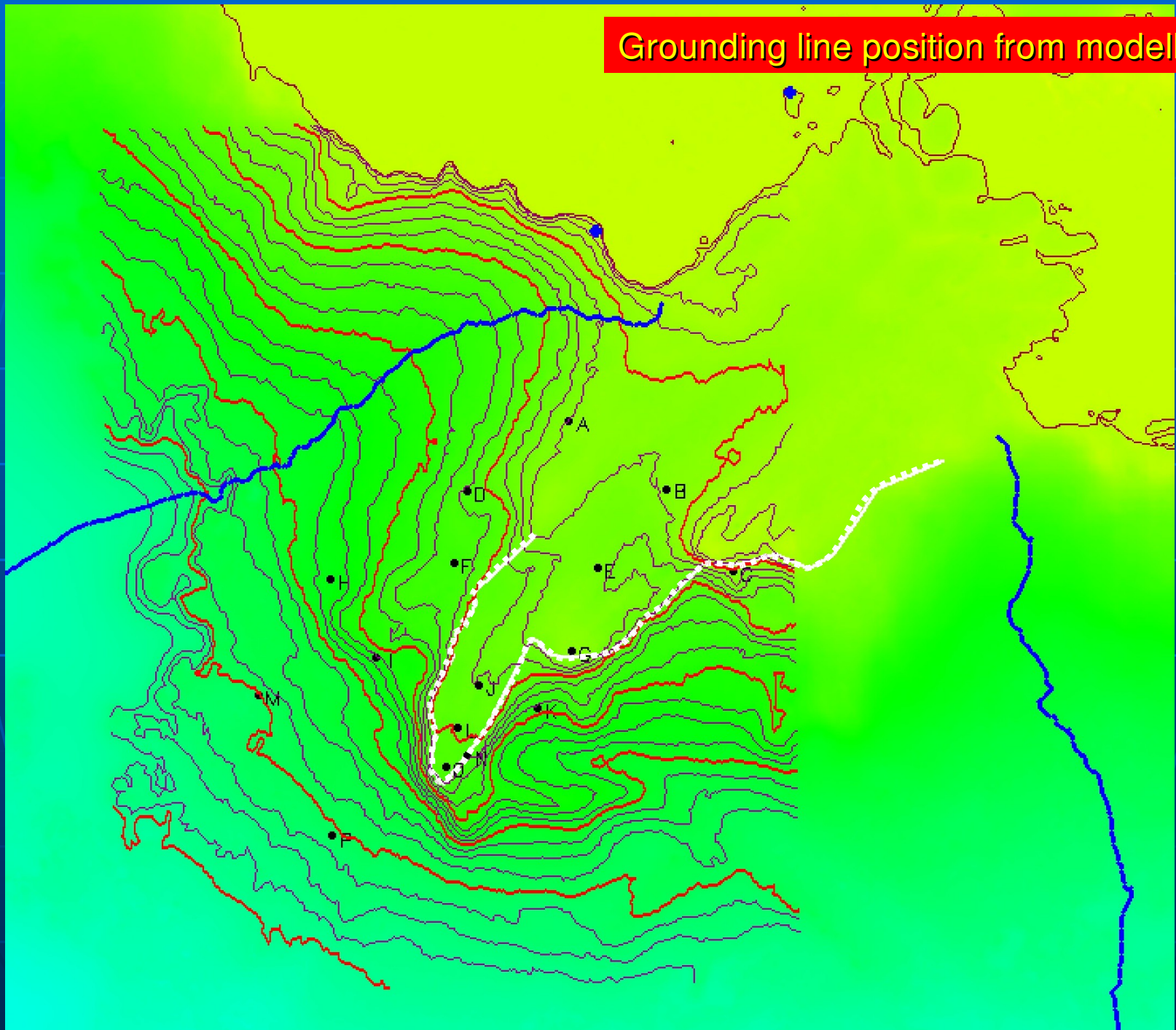
Grounding line position from modelling



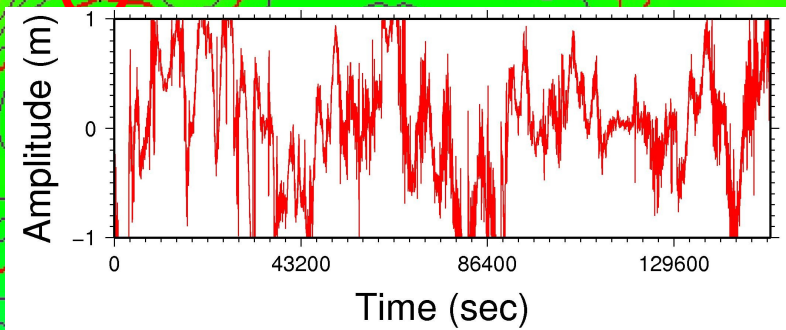
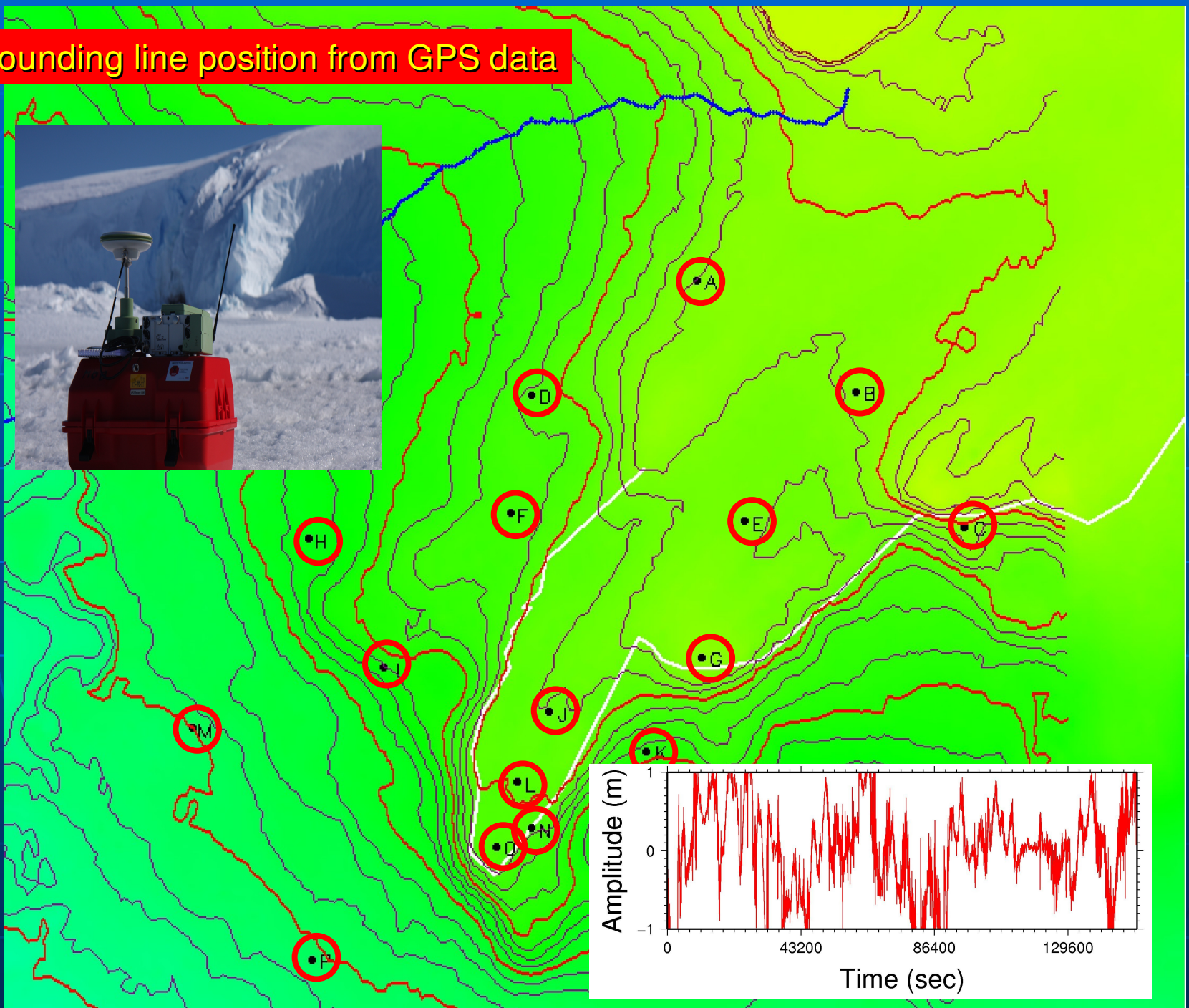
Grounding line position from modelling



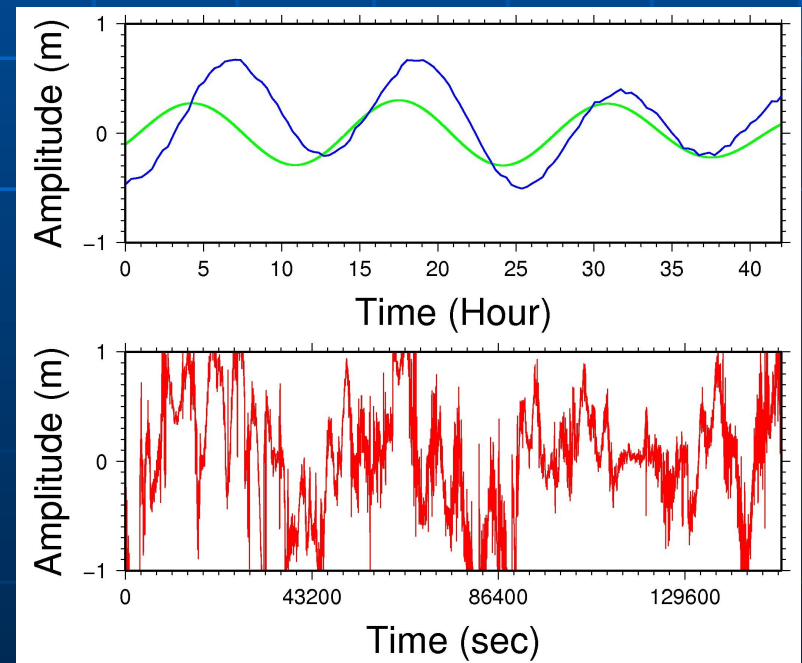
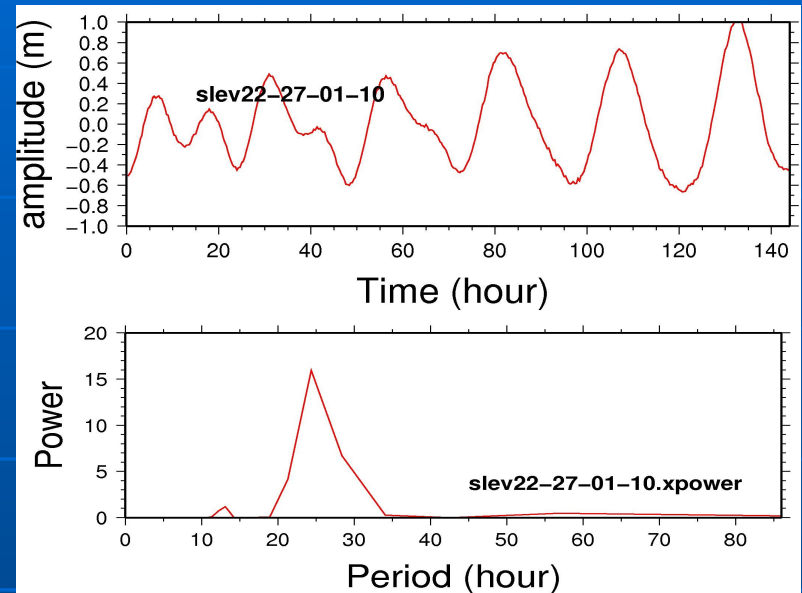
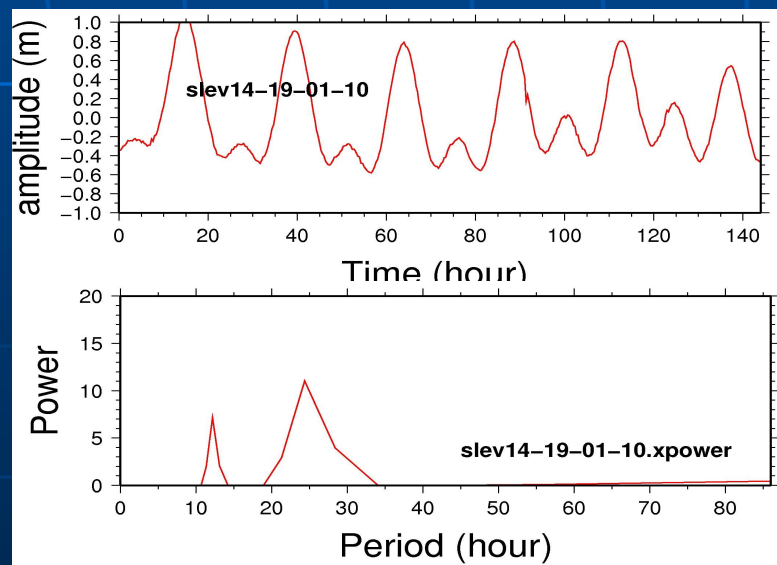
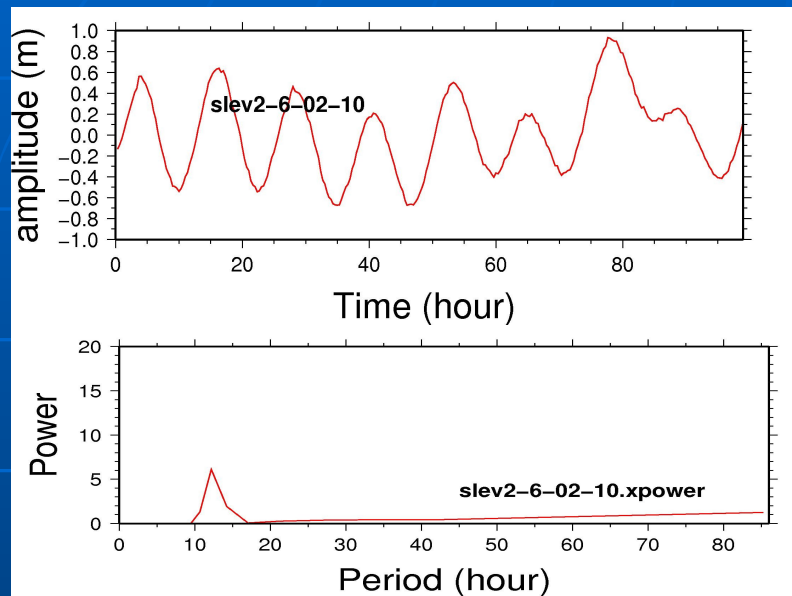
Grounding line position from modelling



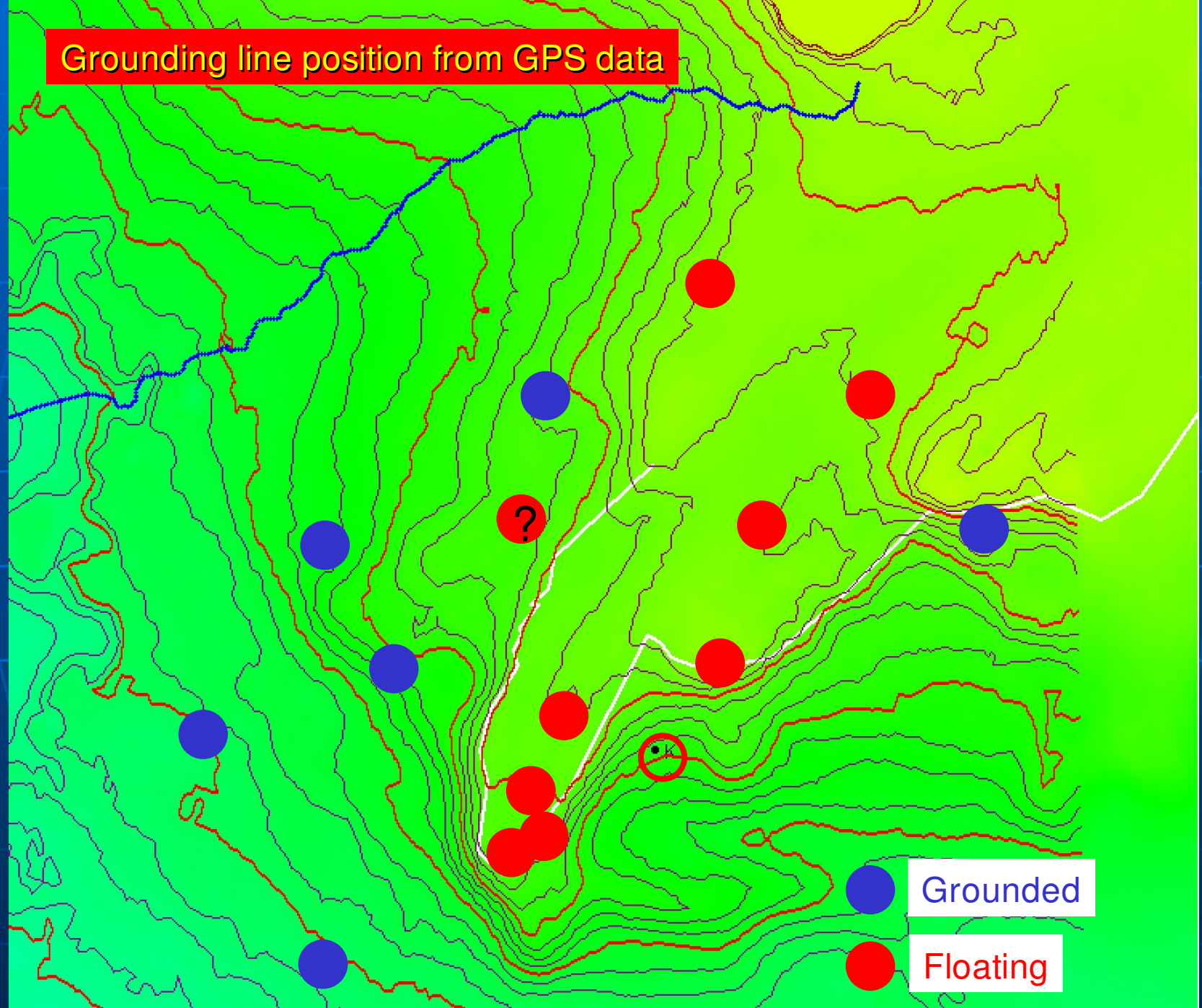
Grounding line position from GPS data



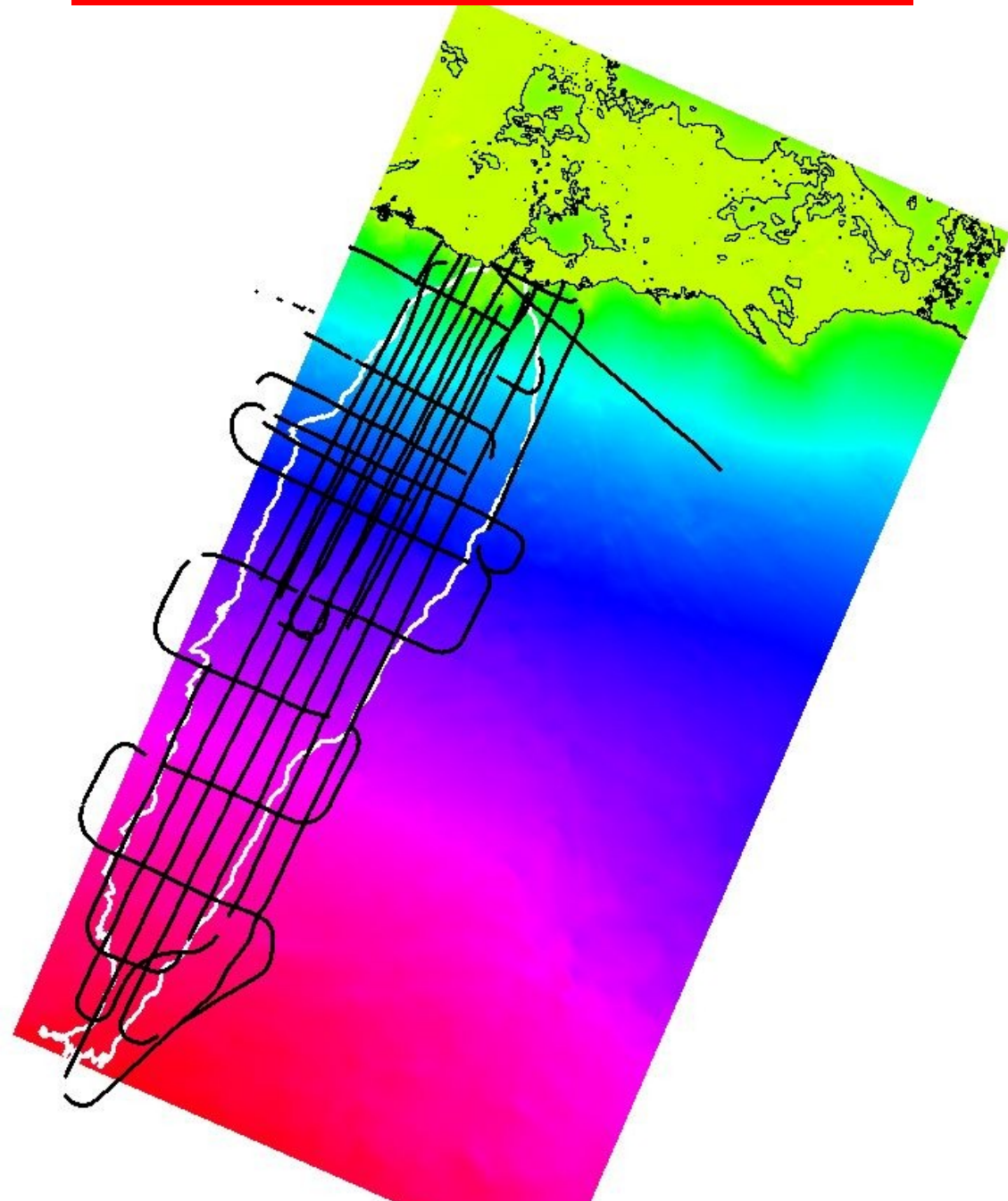
Grounding line position from GPS data



Grounding line position from GPS data



Geophysical airborne campaign (UT-JPL)



JPL 2.5MHz radar
(red grid)



Geophysical airborne campaign (UT-JPL)

Aircraft GPS positioning
+ Double travel time of
radar wave in the air

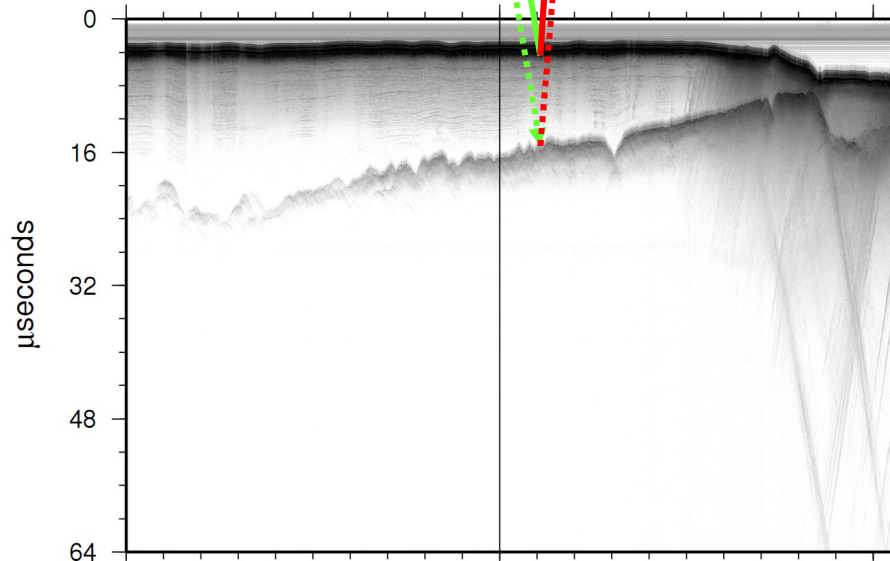
Surface elevation

Bedrock topography

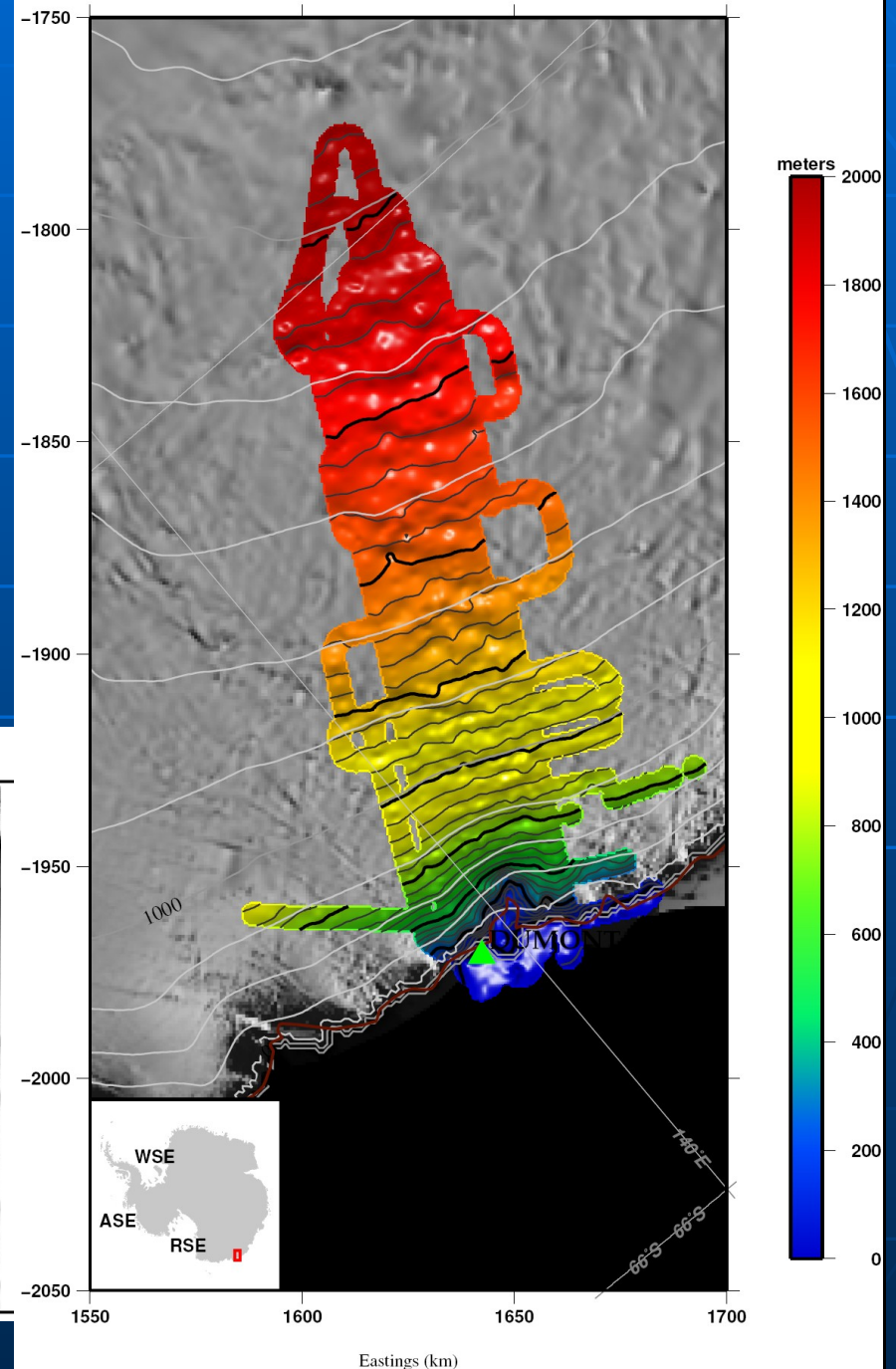


ALG/JKB 1a/X05a

Channel 1

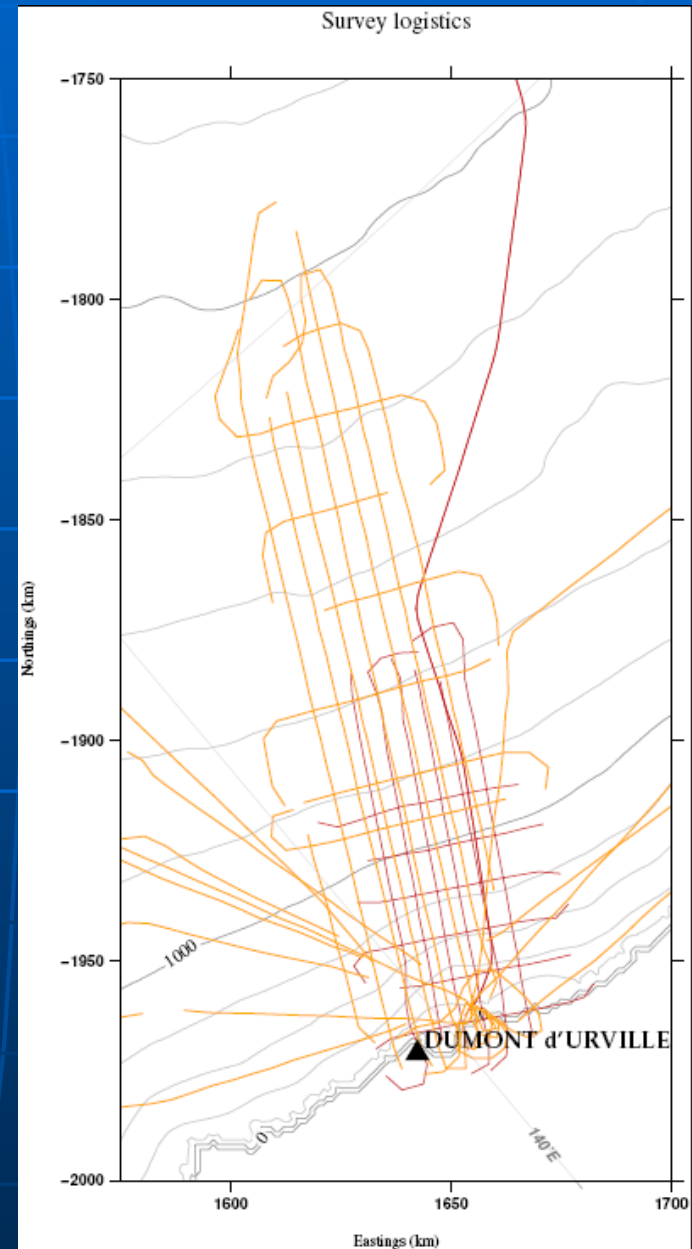


ALG Surface Elevation (WGS-84)

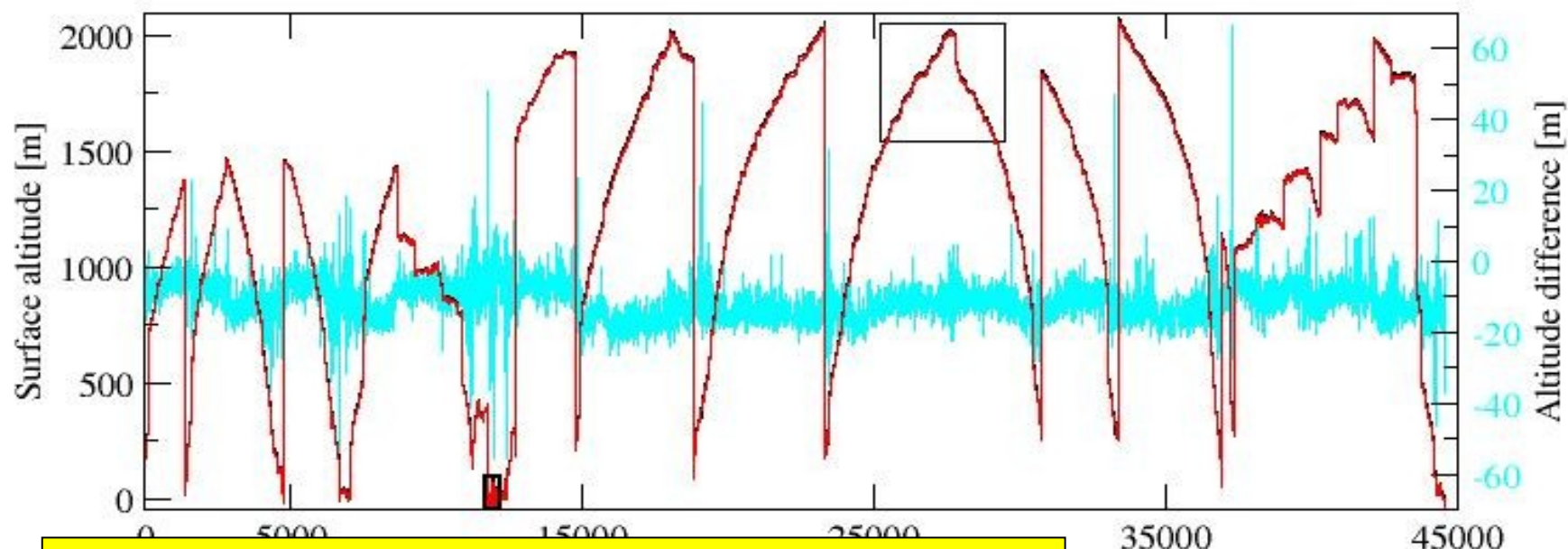


SPIRIT DEM compared with the ICECAP surface data set

42 000 radar points
-> nearest SPIRIT grid point

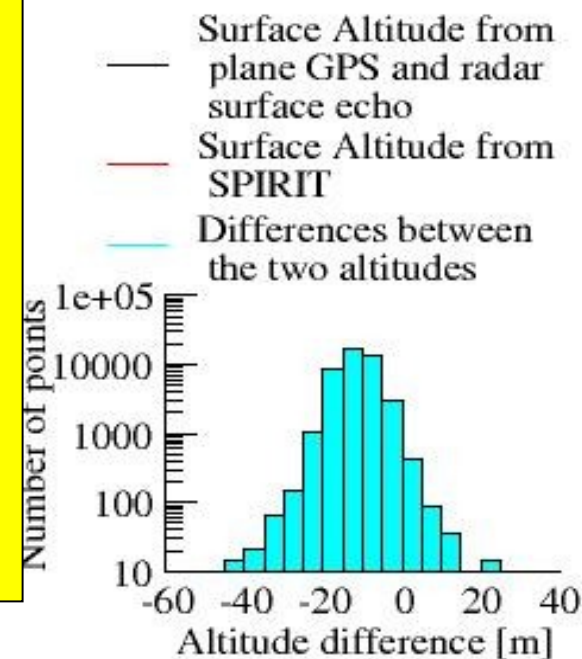


SPIRIT DEM compared with the ICECAP surface data set

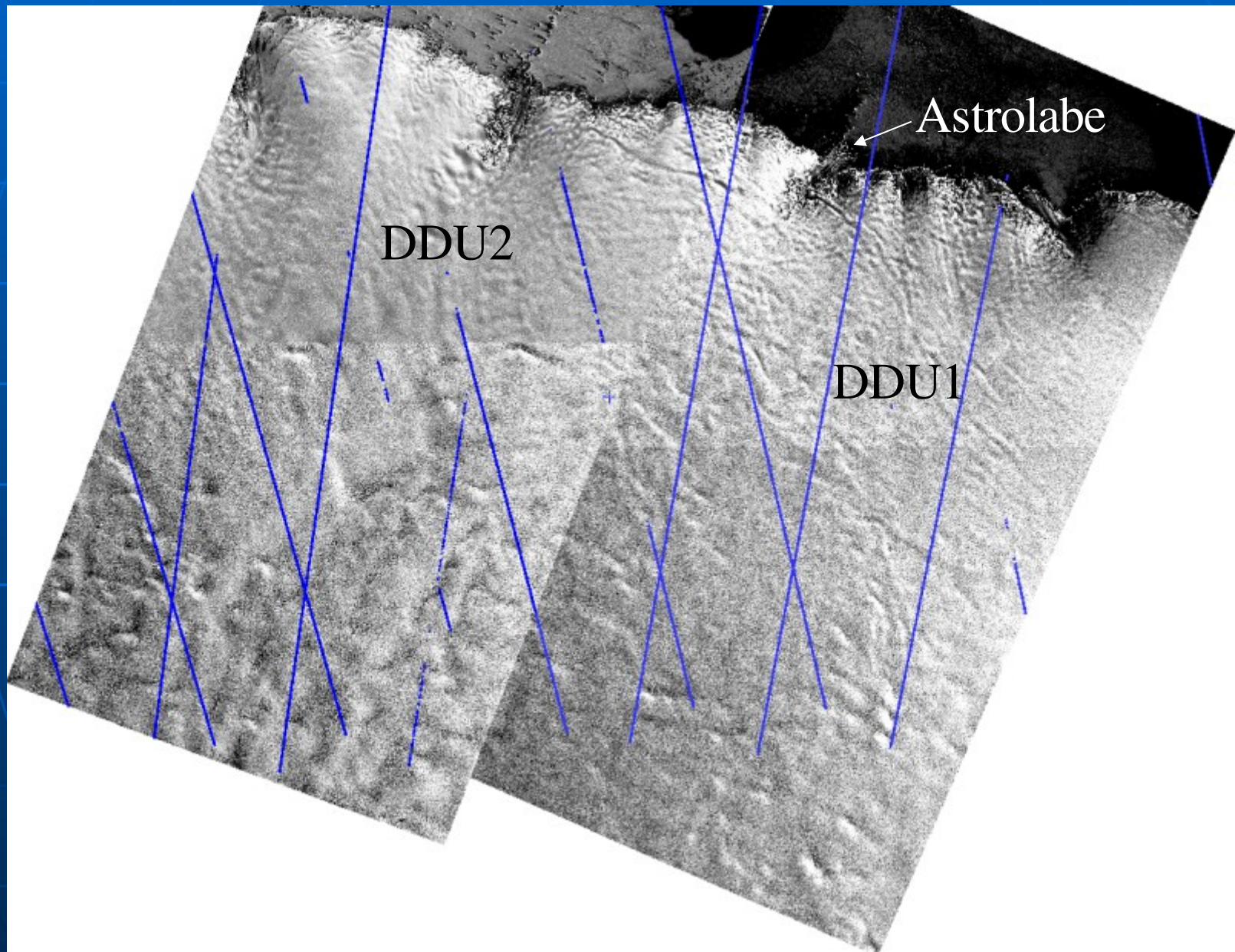


SPIRIT – ICECAP : 5.8 m RMS difference

Aircraft positionning : no carrier phase yet
Carrier phase -> increased accuracy



DDU



DDU 2 : compa HRS - ICESAT

		HRS DEM v1	HRS DEM v2	HRS DEM v3
With interpolated pixels (=all data)	mean	0.43	15.15	15.31
	stddev	18.65	79.29	74.11
	Nb data	4946	4946	4946
Without interpolated pixels	mean	-1.44	-1.46	-1.62
	stddev	3.73	2.78	2.82
	Nb data	1399	1419	545
% of interpolated pixels		56	53	71

DDU 1: compa HRS - ICESAT

			HRS DEM v1	HRS DEM v2	HRS DEM v3
With interpolated pixels (=all data)		mean	6.25	4.60	3.35
		stddev	27.05	21.88	14.97
		Nb data	4520	4520	4520
Without interpolated pixels		mean	-0.29	-0.30	-0.34
		stddev	2.86	2.24	2.36
		Nb data	2329	2175	957
% of interpolated pixels			33	33	54



Thank you !